

PUMA 2100/2600/3100 series

High-Performance Turning Center



High-Performance Turning Center

PUMA 2100/2600/3100 series has been developed to create full line up of high level 8" to 12" size with model variations from 2 axis to Y axis and sub spindle.

PUMA 2100/2600/3100 series







High Performance

These Doosan machines offer a high level of machining capability to provide optimum productivity for the customer.

PUMA 2100/2600/3100 series

Rigid Bed

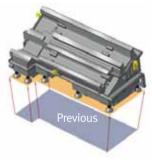
Today's high speed / high acceleration, deceleration feed drives impose severe impact forces on the machine tool structure. This causes low frequency / large amplitude vibration which can cause deterioration in surface finish and contour definition during finish machining. Doosan's enhanced structural stability reduces the effects of vibration and provides the optimum conditions for producing unsurpassed workpiece quality.

Larger than previous

Max. **158** %

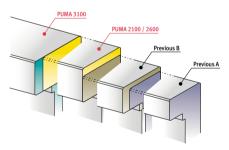
(PUMA 2100 / 2600)

Max. **154** % (PUMA 3100)



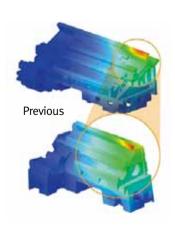
Bed guide way width

For structural stability, the guide way width and span are enlarged by 25%~50%, so that high precision in cutting is ensured.

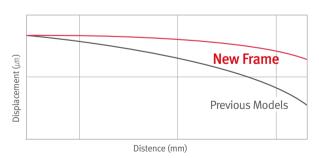


Stiffness

Static and Dynamic rigidity of the new PUMA 2100/2600/3100 machines have been enhanced in structural analysis compared with the previous model.



Guide way deformation



Static stiffness is $\frac{3}{1}$ times higher than previous



Main Spindle

Increased mounting area of headstock base to the bed

The spindle headstock has increased rigidity due to the wide surface contact between the headstock and bed way for Heavy duty cutting, Optimum surface finish, High cutting speeds, Highly accurate roundness.

larger area than previous

Max. 190 %

in the same cl

(in the same class)



Sub Spindle

Mounting base area is

50 % ~ 94 %

larger than previous

Previous Model 135 / 170 mm (5.3 / 6.7 inch)

Chuck size

PUMA 2100 / 2600

175 mm (6.88 inch)



Tooling System (On Turn-Milling)

The turret accommodates BMT55P or BMT65P tooling in which the toolholders are mounted directly to the turret's periphery with 4 large bolts. This type of mounting system BMT55P is standard on PUMA2100 turn-milling models and BMT65P is standard on PUMA2600 and PUMA3100 turn-milling models. BMT65P is available on PUMA2100 as an option.

Max. rotary tool spindle speed

5000 r/min

Max. rotary tool spindle power

5.5 kW (7.3 Hp), 15 min. {7.5 kW (10.1 Hp), 5 min.}

Max. rotary tool spindle torque

47 N·m (34.6 ft-lbs) {95.5 N·m (70.4 ft-lbs)} •••

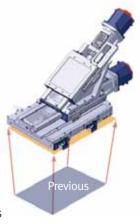


Saddle

The broad width and long contact span of the saddle slideway ensures stability of the support structure. This coupled with the optimised spindle and bed design provides heavy duty and accurate machining capability.

Saddle guide width and span are increased in a range from

Max. 30 % to 46 % compared with previous



Machining Capacity

More powerful revolving motor is adapted to improve the productivity.



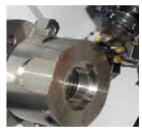
End mill Carbon steel (SM45C)

	Unit	PUMA 2100 BMT55P	PUMA 2600 BMT65P
Chip removal rate	cm³/min (inch³/min)	90 (35.43)	105 (41.34)
Tool Dia.	mm (inch)	18 (0.71)	20 (0.79)
Cutting Depth	mm (inch)	20 (0.79)	21 (0.83)
Feedrate	mm/min (ipm)	250 (9.8)	250 (9.8)



Tapping Carbon steel (SM45C)

	Unit	PUMA 2100 BMT55P	PUMA 2600 BMT65P
Rotary tool spindle speed	r/min	240	240
Tap Size		M20 x P2.5	M24 x P3
Feedrate	mm/min (ipm)	600 (23.6)	600 (23.6)



Face mill Carbon steel (SM45C)

	Unit	PUMA 2100 BMT55P	PUMA 2600 BMT65P
Chip removal rate	cm³/min (inch³/min)	41.9 (16.49)	53.9 (21.22)
Tool Dia.	mm (inch)	63 (2.48)	63 (2.48)
Cutting Depth	mm (inch)	3.5 (0.14)	4.5 (0.18)
Feedrate	mm/min (ipm)	190 (7.5)	190 (7.5)



O.D turning

O.D turning			Carbon steel (SM45C)	
	Unit	PUMA 2100	PUMA 2600	
Chip removal rate	cm³/min (inch³/min)	528 (207.87)	616 (242.52)	
Cutting Depth	mm (inch)	4.3 (0.17)	5.0 (0.2)	
Feedrate	mm/rev (ipr)	0.55 (0.022)	0.55 (0.022)	



U-Drill dia. 63 mm (2.5 inch)

Carbon steel (SM45C)

	Unit	PUMA 2100	PUMA 2600
Chip removal rate	cm³/min (inch³/min)	472 (185.83)	630 (248.03)
Feedrate	mm/min (ipm)	0.15 (0.006)	0.2 (0.008)



Grooving

Feedrate

Carbon steel (SM45C) Unit PUMA 2100 PUMA 2600 Chip removal rate cm³/min (inch³/min) 169 (66.54) 241 (94.9) **Cutting Depth** 8 (0.31) 8 (0.31) mm (inch)

0.14 (0.006)

0.2 (0.008)

mm/rev (ipr)

[•] The results indicated in this catalogue are provided as example. They may not be obtained due to differences in cutting conditions and environmental conditions during measurement.

[•] Turing results are obtained in the condition of standard motor.

Accuracy

Doosan offers its customers unsurpassed levels of accuracy by applying the latest design techniques and rigorous testing processes.

Roundness

		_
Machine	PUMA 2600SY	90°
Macilile	[Belt-driven]	
Tool	TNMG16404R-W	180°
Tool	[Nose radius 0.4mm]	
	ø60 x L50	
Workpiece	(ø2.4 x L2.0 inch)	270'
	Carbon steel [SM45C]	0.5μm
Spindle Speed	3500 r/min	(0.02 µinch)
Cutting Depth	0.025 mm (0.001 inch)	test model
Feedrate	0.025 mm/rev (0.001 ipr)	_ PUMA 2600SY

Users enjoy stable performance in all types of operations from heavy-duty cutting to high speed machining.

Work material	Aluminum (AL2024)	
Cutting speed	250 (9842.5) m/min (ipm)	
Feedrate	0.08 (0.003) mm/rev (ipr)	
Cutting depth	0.2 (0.008) mm (inch)	
Tool	Diamond [nose R0.8]	

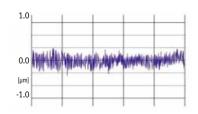
PUMA 2600SY	0.5	
Current PUMA		3.2

Roughness

Ra 0.11µm (Ra 0.004 µinch)

Rz 0.83µm (Rz 0.033 µinch)

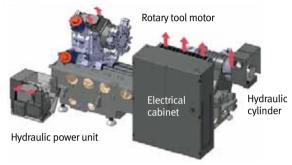
Rmax 0.92µm (Rmax 0.036 µinch)



Material	Carbon steel (SM45C)	
Work Size	ø60 x L50 mm (ø2.4 x L2.0 inch)	
Spindle speed	3500 r/min	
Feed	0.025 mm/rev (0.001 ipr)	
Depth	0.025 mm (0.001 inch)	
Holder	PTGNR2020 M16	
Insert	TNMG160404 R-W (R0.4)	

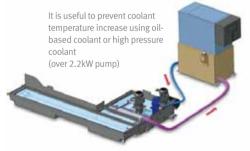
Heat elimination layout

One very important design concept is to reduce the effects of heat sources in the machine. Heat shields and fan motors are used to prevent the transmission of heat to the machine structure.



Coolant chiller on

Thermal displacement and dimensional accuracy are greatly influenced by oil temperature in a machine. Coolant Temperature Control unit prevents the coolant from heating. Especially, when using oil-based coolant, the oil temperature can become extremely high.



* Please contact Doosan in these cases

Inertia estimates function for C-axis 410



This function can estimate the C-axis inertia which is affected by variation in workpiece weight. It is possible to optimise the Velocity Gain and Acc/Dec Time Constant and therefore improve the C-axis accuracy.

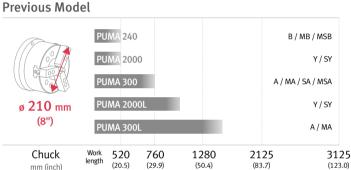




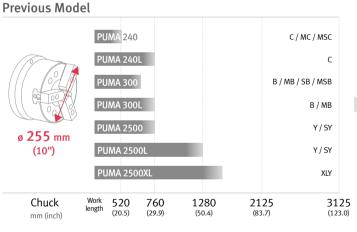
Wide Variation

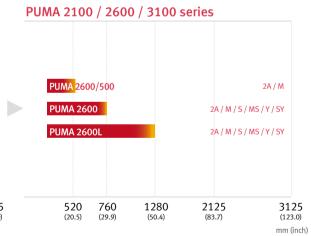
A wide variety of machine specifications from 2-axis models to turning centers with sub spindles is available to meet your production requirements.

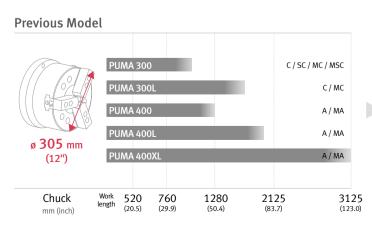
PUMA 2100/2600/3100 series

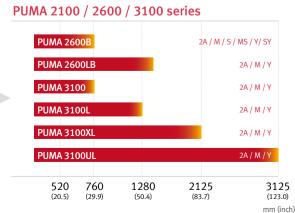


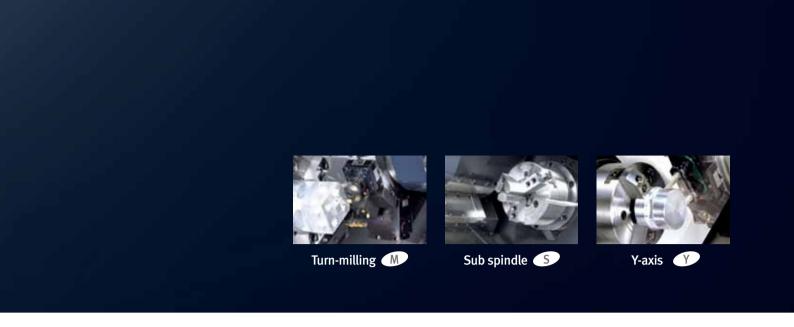














PUMA 2100

Turning		Turn-milling	
std. 1 S	LS	M LM	MS LMS
		Y	SY LSY
Max. work length		mm (inch)	520 / 760 [L] (20.5 / 29.9 [L])
Chuck [Main / Sub]		mm (inch)	210 / 175 (8 / 6)
Max. turning dia.		mm (inch)	480, 406 ¹⁾ {376 ²⁾ } (18.9,16.0 ¹⁾ {14.8 ²⁾ })
	X-axis	mm (inch)	260 (10.2)
Travel	Z-axis	mm (inch)	590 / 830 [L] (23.2 / 32.7 [L])
	Y-axis	mm (inch)	105 (±52.5) (4.1(±2.1))

{}:Option



PUMA 2600*

Turning		Turn-millin	
std. 1 S	LS	M LM	MS LMS M/500 MB LMB MSB LMSB
/500 B LB	SB LSB	Y	SY LSY YB LYB SYB LSYB
Max. work length		mm (inch)	520 (500 machine) / 760 / 1280 [L] (20.5 / 29.9 / 50.4 [L])
Chuck [Main / Sub]		mm (inch) 255 / 175 (10 / 6)	
Max. turning dia.		mm (inch)	480, 376 ²⁾ (18.9, 14.8 ²⁾)
	X-axis	mm (inch)	260 (10.2)
Travel	Z-axis	mm (inch)	590 (500 machine) / 830 / 1350 [L] (23.2 / 32.7 / 53.1 [L])
	Y-axis	mm (inch)	105 (±52.5) (4.1(±2.1))

^{* :} PUMA 2600B Chuck size: 305 mm (12.0 inch)

{}:Option



- 1) : PUMA 2100M [LM] / MS [LMS] / Y [LY] / SY [LSY] 2) : PUMA 2100, 2600M [LM] / MS [LMS] / Y [LY] / SY [LSY] 3) : PUMA 3100M/LM/XLM/ULM/Y/LY/XLY/ULY

PUMA 3100

std.		OL)	Y LY XLY ULY
			760 / 1280 [L] (29.9 / 50.4 [L])
Max. work	length	mm (inch)	2125 [XL] / 3125 [UL]
			(83.7 [XL] / 123.0 [UL])
Chuck [Main]		mm (inch)	305 (12)
Max. turning dia.		mm (inch)	525, 420 ³⁾ (20.7, 16.5 ³⁾)
	X-axis	mm (inch)	293 (10.2)
	- .	6 1)	830 / 1350 [L] / 2190 [XL] / 3190 [UL]
Travel	Z-axis	mm (inch)	(32.7 / 53.1 [L] / 86.2 [XL] / 125.6 [UL])
	Y-axis	mm (inch)	130 (±65) (5.1 (±2.6))

{}:Option

Machining range

We have added a high-rigidity bed and special functions and equipment for machining long workpieces. It is the definitive bar workmachine, eliminating all compromise.



Model	A (Max. turning length)	B (Max. turning diameter)	C (Door open space)
PUMA 2100 / S	F20 (20 F)	480 (18.9)	(05 (27 /)
PUMA 2100M / MS / Y / SY	520 (20.5)	406 (16.0)	695 (27.4)
PUMA 2100L / LS	7(0 (20 0)	480 (18.9)	015 (22.1)
PUMA 2100LM / LMS / LY / LSY	760 (29.9)	406 (16.0)	815 (32.1)
PUMA 2600 / S	7(0 (20 0)	480 (18.9)	015 (22.1)
PUMA 2600M / MS / Y / SY	760 (29.9)	376 (14.8)	815 (32.1)
PUMA 2600L / LS	1280 (50.4)	480 (18.9)	1375 (54.1)
PUMA 2600LM / LMS / LY / LSY	1200 (50.4)	376 (14.8)	13/3 (34.1)
PUMA 2600/500	F20 (20 F)	480 (18.9)	(05 (27 4)
PUMA 2600M/500	520 (20.5)	376 (14.8)	695 (27.4)
PUMA 2600B/LB	725 / 1245	480 (18.9)	815 (32.1)
PUMA 2600MB/LMB	(28.5 / 49.0)	376 (14.8)	015 (52.1)
PUMA 2600SB/MSB	725 (28.5)	480 / 376 (18.9 / 14.8)	815 (32.1)
PUMA 2600YB/SYB	723 (20.3)	376 (14.8)	015 (52.1)
PUMA 3100	760 (29.9)	525 (20.7)	850 (33.5)
PUMA 3100M / Y	760 (29.9)	420 (16.5)	000 (00.0)
PUMA 3100L	1280 (50.4)	525 (20.7)	1440 (56.7)
PUMA 3100LM / LY	1200 (50.4)	420 (16.5)	1440 (56.7)
PUMA 3100XL	2125 (83.7)	525 (20.7)	2260 (89.0)
PUMA 3100XLM / XLY	2123 (03.7)	420 (16.5)	2200 (03.0)
PUMA 3100UL	3125 (123.0)	525 (20.7)	3260 (128.3)
PUMA 3100ULM / ULY	3123 (123.0)	420 (16.5)	J200 (120 . 3)

Unit: mm (inch)

Main spindle

To achieve a high level of stability during machining, improvements in rigidity have been the main focus in the design process. The mounting areas of main and Sub-spindles have been significantly widened and the spindle length shortened to minimise vibration. Spindle bearing diameter has been increased to improve rigidity. This also allows a larger through bore size for the sub-spindle. Spindles are available as belt type or built-in motor type.

Bar work capacity

PUMA 3100

PUMA 2100	Ø65 mm (Ø2.6 inch)
PUMA 2600	Ø76 mm (ø3.0 inch)
PUMA 2600B PUMA 3100	ø102 mm (ø4.0 inch)

Power & torque of spindle

Model	Speed (r/min)	Power [kW (Hp)]	Max. Torque [N·m (ft-lbs)]
PUMA 2100	4500	std. 18.5 (24.8)	183 (135.1)
	5000 [Built-in]	opt. 22 (29.5)	358 (264.2)
PUMA 2600	3500	std. 22 (29.5)	240 (177.1)
	4000 [Built-in]	opt. 22 (29.5)	599 (442.1)
PUMA 2600B	2800	std. 22 (29.5)	1123 (828.8)
PUMA 3100	2800	std. 22 (29.5)	1123 (828.8)
	3000 [Built-in]	opt. 30 (40.2)	1203 (887.8)







Built-in Motor Spindle Type (opt. Y / SY models)



To make rotary tooling more effective, precise circular positioning of the spindle is necessary. The sub-spindle has 0.001° full C-axis contour function which is same with the function of main spindle. Moreover, power and torque are increased for more cutting capability.

Power & torque of spindle

Model	Speed (r/min)	Power [kW (Hp)]	Max. Torque [N·m (ft-lbs)]
PUMA 2100 PUMA 2600	4500	std. 7.5 (10.1)	85 (61.3)
	6000 [Built-in]	opt. 15 (20.1)	134 (98.9)

Enhanced sub-spindle

Model	Previous Model	PUMA 2100 / 2600				
Chuck size	135 / 170 mm (5 / 6 inch)	▶ 175 mm (6 inch)				
Spindle bearing diameter	75 / 90 mm (3.0 / 3.5 inch)	90 mm (3.5 inch)				
Bar capacity	43 / 53 mm (1.7 / 2.1 inch)	▶ 48 mm (1.9 inch)				

Tailstock configuration 29 40 40

3 types of tail stocks such as manual, programmable and servo driven can be offered to customers as alternative choices.

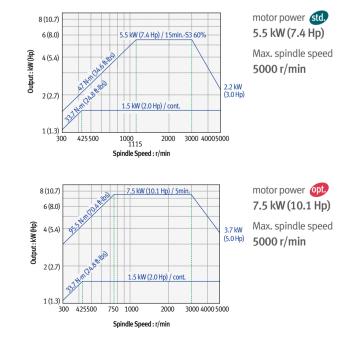
	Model		PUMA 2100 / L series	PUMA 2600 / L series PUMA 3100 / L series	PUMA 3100XL / UL series	
		Live center MT4	std.	Not avaliable		
Manualtura		Built-in center MT3	opt.	Not avaliable		
Manual type	7	Live center MT5	Net a Pala	std.		
		Built-in center MT4	Not avaliable	opt.	Not as all abla	
		Live center MT4		Mar and Palala	Not avaliable	
	-19	Built-in center MT3	opt.	Not avaliable		
Programmable		Live center MT5				
type		Built-in center MT4	Not avaliable	opt.		
		Built-in center MT5			std.	
		Live center MT4		Not avaliable		
Servo driven type		Built-in center MT3	opt.		Martin Palda	
		Live center MT5	Martin Palala		Not avaliable	
		Built-in center MT4	Not avaliable	opt.		

Turret Turn 🗗 🕥 Turn-milling 🐠 🐠 💕

The turret has been designed based on a modular concept. It provides improved tool clearance and optimum rigidity. The milling turret version includes 24 position indexing to increase the available tool capacity.

		Turning PUMA 2100 / 2600 / 3100	Turn-Milling PUMA 2100 / 2600 / 3100				
No. of too							
		12 / 12 / 10 st	12 st {24*st opt, 16**st opt.]				
Tooling sy	stem	Doosan Base	BMT55P / 65P / 65P				
	OD	25 x 25 mm (1.0 x 1.0 inch)				
Tool size	ID	ø50 mm (ø2.0 inch)	ø40 / 50 / 50 mm (ø1.5 / 2.0 / 2.0 inch)				
Curvic cou	pling	ing ø230 mm (9.1 inch)					
Turret inde	ex time	0.15 s					

Rotary tool power torque diagram



In the Y-axis plane, tools can move in a plus or minus direction perpendicular to the Z-axis and spindle center line. Viewed from the operator's perspective, this Y-axis motion is toward or away from the door of the machine while X-axis moves from floor to ceiling. Y-axis enables various shape of cutting. Y-axis is realized virtually by the linear interpolation and synchronous movement of X1 and X2-axis that make it possible to lower machine height for stability.

Y-axis travel

PUMA 2100 / 2600 **105** mm

[±52.5mm] (4.1 inch [±2.1 inch])

PUMA 3100 **130** mm

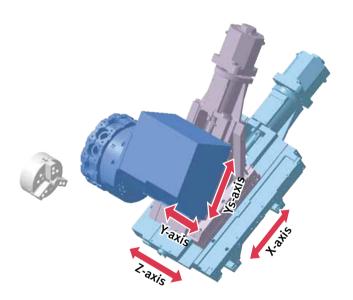
[±65.0mm] (5.1 inch [±2.6 inch])

Y-axis rapid 10 m/min (7.4 ipm)



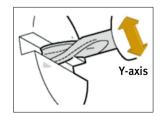
Configuration of Y-axis

Model	PUMA 2100/2600	PUMA 3100			
Bed slant angle	30°	30°			
X slant angle	30°	30°			
X-Y slant angle	30°	30°			
Y-axis travel	±52.5 mm (±2.1 inch)	±65.0 mm (±2.6 inch)			

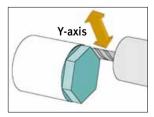


All enough in single setup

Simultaneous XYZ motion provides the capability milling complex shapes. In addition, the rigidly clamped C-axis disc brake enables heavy duty and precision machining.



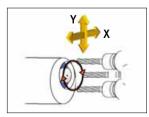
On-center face groove



Poly-side machine



Off-center side groove



Y&X-axis circular interpolation

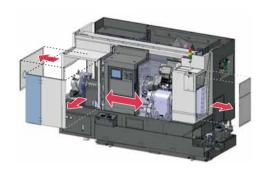
Improved Maintainability

Maintainability is one of the crucial criteria that Doosan placed at the forefront of machine development. Large openings in the machine paneling facilitate access to the underlying maintenance units like lubricant oil tank and pneumatic fittings.

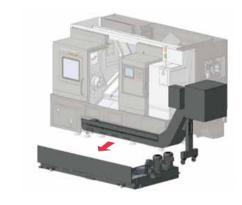
PUMA 2100/2600/3100 series

Easy to Access for Maintenance

By new machine cover design concept, maintenance locations are easily seen, and wider openings allow easier access.

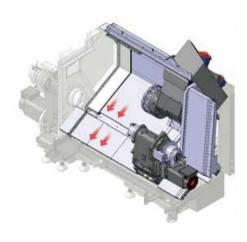


The coolant tank can be pulled out at the front and does not require the chip conveyor to be removed.



Fully Wrapped Machine

To minimize the thermal effect on the machine, heat of chips should be prevented from being transmitted to bed and guide ways. Guide ways are fully covered so that heat can be isolated. Also, telescopic covers have strengthened linkage system that ensures durability. (only PUMA 2100/2600)





Power Saving Function

Automatic machine light turns off

This is smart function that can turn off the machine light automatically when no user touches key board of operation panel during specified time.





Automatic machine sleep

If CNC operator's panel has not been used for a time, the motors for spindle, servo axis, coolant pump and chip conveyor etc. are powered off automatically. It is effective to reduce standby power. Save up stand by power from 10 to 14%.



EZ Function

This function is to support simple setting of Tool Setter and improve the function to set tail stock position automatically with recorded tail stock position.

EZ automatic tail stock function

This function enables the position setting of tail stock automatically. In programmable tail stock, the Z-axis position of tail stock is recorded automatically



as the clamped position of tail stock. When tail stock needs to move to the other position, Z-axis moves to the pre-recorded position of Z-axis and tail stock unclamps by the button operation of OP pane.

EZ tool setter function

This is specially designed for improving the efficiency of CNC turning center. If a user selects target tool to be checked by Tool Setter in manual mode, its moving axis is advanced forward to make the setter easy to touch off the tools, and the axis moves backward after touching the tool automatically.



Easy Operation Package

These DOOSAN software packages have been customized to provide user-friendly functions.

Programming



G Code list

Operator can check the meaning of each G-code.



M Code list

Operator can check the meaning of each M-code.



Calculator

Operator can calcute numerical formula in relation to arc and hole easily.



Servo tailstock thrust setting

Thrust force control is simple to set up using the specially designed servo-driven tail stock thrust setting software.

- Input value directly
- Select one of the initially set values

Operation / Maintenance



Tool load monitor on

The main function of this software is to detect overload when a tool is wrong, and change it to an other tool. Stop machine to protect a tool holder and next tools by detecting overload caused by tool breakage or its wear. Use editable tool life management for spare tools. Monitor load meter for all spindles and axes. If the tool load reaches abnormal band recorded in "Set data", the software issues an feed hold alarm or skips the tool.



Operation rate - user log in

A major determinant of efficiency is the cost associated with setting up the equipment to make a particular product. This software can be used to manage machine operation rate of 3 operators. Total machine operation and real machining time for a month can be recorded and measured. It helps to evaluate and monitor each operational efficiency. To keep it secure, Password setting is essential.



Back up custom data

This can be used to record tool load information detected in "Tool load monitor" for all tools used during cutting. By reloading recorded data in tool table, Tool Load Monitor software can compare the actual tool load with a recorded load pattern.



Turret recovery help

The software is to help users recover turret step by step from trouble situation where it does not work. It can quickly recover your valuable machine.

Easy Guide i

Operation Guidance, which supports entire operations on an all-in-one screen for daily machining including creating a program on the machine.

- Uses one display screen to perform all operations including programming, checking by animation, and real machining.
- User-Friendly Operation : Soft key selection of comprehensive cycle library
- Easy programming
 Based on ISO-code program format, complex machining motions can be created easily by this menu format.
- Machine status window
 Machine status such as actual position,
 feedrate and load meter are always displayed.
- Realistic machining simulation
 3-D solid model machining simulation is available.
- Intuitive menu selecting
 Menu can be selected easily and intuitively by soft-keys with icons.



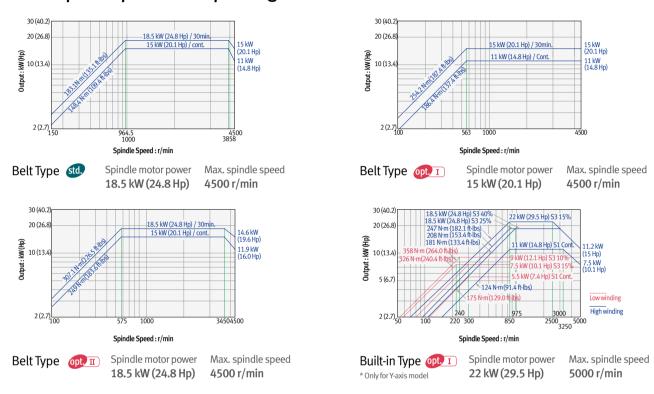
Cycle machining menus for both of lathe machining and milling are available



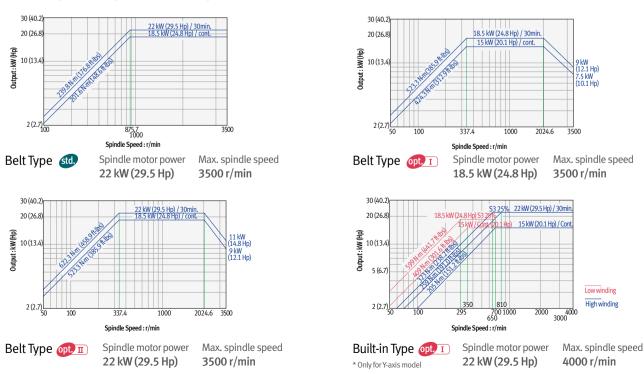
Programming time can be reduced

Spindle Power - Torque Diagram

Main spindle power - torque diagram PUMA 2100 series

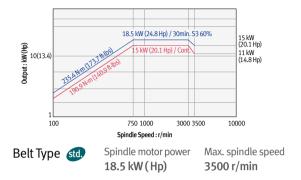


Main spindle power - torque diagram PUMA 2600 series

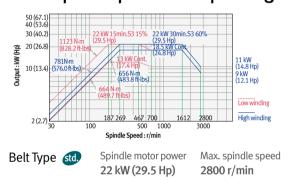


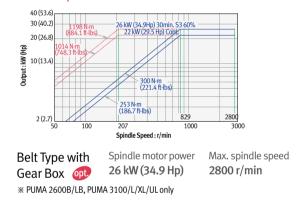
Spindle Power - Torque Diagram

Main spindle power - torque diagram PUMA 2600 / 500, PUMA 2600M / 500

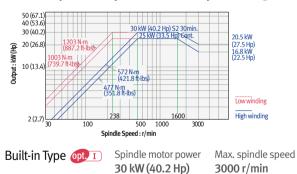


Main spindle power - torque diagram PUMA 2600B / 3100 series

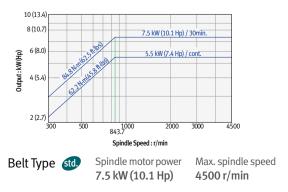


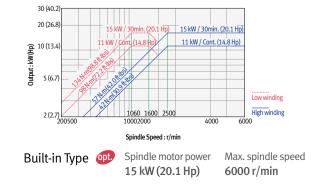


Main spindle power - torque diagram PUMA 3100 series



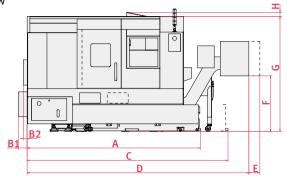
Sub spindle power - torque diagram PUMA 2100 / 2600

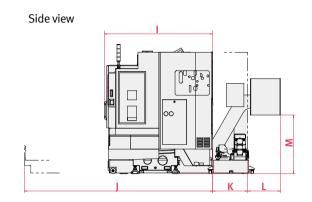




PUMA 2100 Unit: mm (inch)







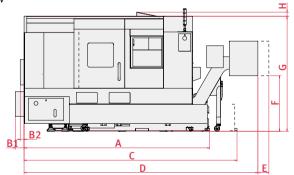
Model	А	B1	B2	С	D	E	F	G	Н	I	J	K	L	М
PUMA 2100/S/M/MS	3150 (124.0)	160 (6.3)	-	3650 (143.7)	4030 (158.7)	200 (7.9)	1010 (39.8)	1903 (74.9)	-	1863 (73.3)	3240 (127.6)	523 (20.6)	646 (25.4)	1007 (39.6)
PUMA 2100Y/SY	3150 (124.0)	160 (6.3)	25 (1.0)	3650 (143.7)	4030 (158.7)	200 (7.9)	1010 (39.8)	2090 (82.3)	73 (2.9)	1863 (73.3)	3240 (127.6)	523 (20.6)	646 (25.4)	1007 (39.6)
PUMA 2100L/LS/LM/LMS	3370 (132.7)	160 (6.3)	-	3870 (152.4)	4250 (167.3)	200 (7.9)	1010 (39.8)	1903 (74.9)	-	1863 (73.3)	3240 (127.6)	523 (20.6)	646 (25.4)	1007 (39.6)
PUMA 2100LY/LSY	3370 (132.7)	160 (6.3)	25 (1.0)	3870 (152.4)	4250 (167.3)	200 (7.9)	1010 (39.8)	2090 (82.3)	73 (2.9)	1863 (73.3)	3240 (127.6)	523 (20.6)	646 (25.4)	1007 (39.6)

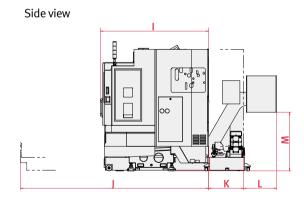
B1: Belt type. Standard Spindle Motor, Optional Spindle Motor is different.

B2 : Built-In type.

PUMA 2600 Unit: mm (inch)



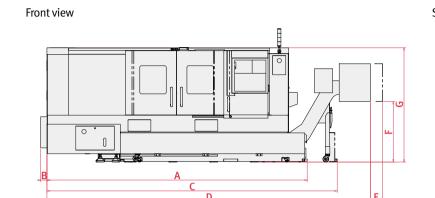


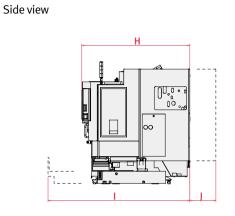


Model	Α	B1	B2	С	D	E	F	G	Н	ı	J	К	L	М
PUMA 2600/500 PUMA 2600M/500	3150 (124.0)	220 (8.7)	-	3650 (143.7)	4030 (158.7)	200 (7.9)	1010 (39.8)	1903 (74.9)	-	1863 (73.3)	3240 (127.6)	523 (20.6)	646 (25.4)	1007 (39.6)
PUMA 2600/S/M/MS	3370 (132.7)	230 (9.1)	-	3870 (152.4)	4250 (167.3)	200 (7.9)	1010 (39.8)	1903 (74.9)	-	1863 (73.3)	3240 (127.6)	523 (20.6)	646 (25.4)	1007 (39.6)
PUMA 2600B/SB/MB/MSB	3370 (132.7)	333 (13.1)	-	3870 (152.4)	4250 (167.3)	200 (7.9)	1010 (39.8)	1903 (74.9)	-	1863 (73.3)	3240 (127.6)	523 (20.6)	646 (25.4)	1007 (39.6)
PUMA 2600Y/SY	3370 (132.7)	230 (9.1)	135 (5.3)	3870 (152.4)	4250 (167.3)	200 (7.9)	1010 (39.8)	2090 (82.3)	73 (2.9)	1863 (73.3)	3240 (127.6)	523 (20.6)	646 (25.4)	1007 (39.6)
PUMA 2600YB/SYB	3370 (132.7)	333 (13.1)	-	3870 (152.4)	4250 (167.3)	200 (7.9)	1010 (39.8)	2090 (82.3)	73 (2.9)	1863 (73.3)	3240 (127.6)	523 (20.6)	646 (25.4)	1007 (39.6)

 ${\tt B1:Belt\,type.Standard\,Spindle\,Motor,\,Optional\,Spindle\,Motor\,is\,different.}$ ${\tt B2:Built-In\,type.}$

PUMA 2600L Unit: mm (inch)

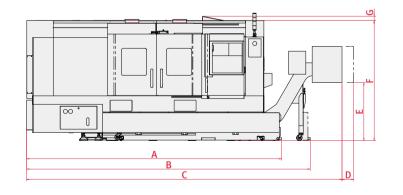


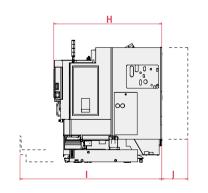


Model	Α	В	С	D	E	F	G	Н	I	J
PUMA 2600L/LS/LM/LMS	4335 (170.7)	-	4835 (190.4)	5389 (212.2)	200 (7.9)	1010 (39.8)	1903 (74.9)	1965 (77.4)	3240 (127.6)	523 (20.6)
PUMA 2600LB/LSB/LMSB	4335 (170.7)	103 (4.1)	4835 (190.4)	5389 (212.2)	200 (7.9)	1010 (39.8)	1903 (74.9)	1965 (77.4)	3240 (127.6)	523 (20.6)

PUMA 2600LY
Unit: mm (inch)

Front view Side view

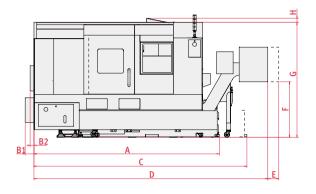




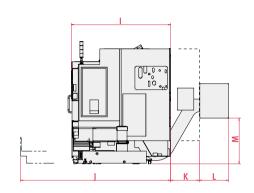
Model	Α	В	С	D	E	F	G	Н	I	J
PUMA 2600LY/LSY/LYB/LSYB	4435	4935	5489	200	1010	2090	73	1965	3240	523
	(174.6)	(194.3)	(216.1)	(7.9)	(39.8)	(82.3)	(2.9)	(77.4)	(127.6)	(20.6)

PUMA 3100 Unit: mm (inch)

Front view



Side view

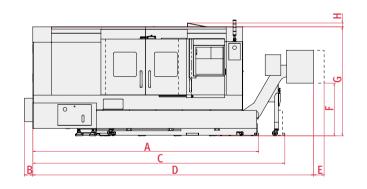


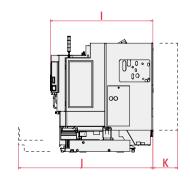
Model	А	B1	B2	С	D	E	F	G	Н	ı	J	K	L	М
PUMA 3100/M	3575	332	250	4095	4486	200	1010	1997	20	2003	3410	523	646	1007
	(140.7)	(13.1)	(9.8)	(161.2)	(176.6)	(7.9)	(39.8)	(78.6)	(0.8)	(78.9)	(134.3)	(20.6)	(25.4)	(39.6)
PUMA 3100Y	3575	332	250	4095	4486	200	1010	2214	105	2003	3410	523	646	1007
	(140.7)	(13.1)	(9.8)	(161.2)	(176.6)	(7.9)	(39.8)	(87.2)	(4.1)	(78.9)	(134.3)	(20.6)	(25.4)	(39.6)

B1 : Belt type. Standard Spindle Motor, Optional Spindle Motor is different. B2 : Built-In type.

PUMA 3100L Unit: mm (inch)

Front view Side view





Model	А	В	С	D	E	F	G	Н	I	J	К
PUMA 3100L/LM	4455	72	5135	5527	50	1010	1997	20	2105	3410	523
	(175.4)	(2.8)	(202.2)	(217.6)	(2.0)	(39.8)	(78.6)	(0.8)	(82.9)	(134.3)	(20.6)

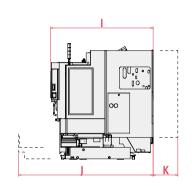
PUMA 3100LY

Front view

A B C



Side view

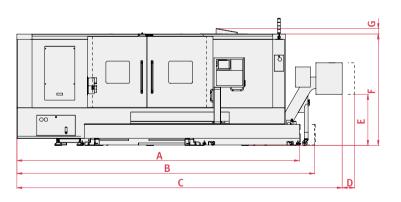


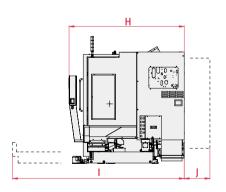
Model	А	В	С	D	E	F	G	I	J	K
PUMA 3100LY	4530	5210	5602	50	1010	2214	105	2105	3410	523
	(178.4)	(205.2)	(220.6)	(2.0)	(39.8)	(87.2)	(4.1)	(82.9)	(134.3)	(20.6)

PUMA 3100XL / UL

Unit:mm (inch)







Model	А	В	С	D	E	F	G	Н	ı	J
PUMA 3100XL/XLM	5615 (221.1)	6015 (236.8)	6443 (253.7)	245 (9.6)	1010 (39.8)	2208 (86.9)	-	2280 (89.8)	3400 (133.9)	523 (20.6)
PUMA 3100XLY	5615 (221.1)	6015 (236.8)	6443 (253.7)	245 (9.6)	1010 (39.8)	2208 (86.9)	107 (4.2)	2280 (89.8)	3400 (133.9)	523 (20.6)
PUMA 3100UL/ULM	6585 (259.3)	7265 (286.0)	7670 (302.0)	268 (10.6)	1010 (39.8)	2208 (86.9)	-	2280 (89.8)	3400 (133.9)	523 (20.6)
PUMA 3100ULY	6585 (259.3)	7265 (286.0)	7670 (302.0)	268 (10.6)	1010 (39.8)	2208 (86.9)	107 (4.2)	2280 (89.8)	3400 (133.9)	523 (20.6)

Standard & Optional Features

lacktriangle: standard features \bigcirc : option \triangle : Pre-discussion is required \times : Not available

Oution		PU	MA 2100(L) / 2600(L)		PUMA	A 3100 St	d./L	PUMA	PUMA 3100 XL/UL		
Option	2-axis Std.	M	S	MS	Υ	SY	2-axis Std.	М	Υ	2-axis Std.	M	Υ	
Special chucks	Δ	Δ	Δ	Δ	Δ	Δ	Δ	Δ	Δ	Δ	Δ	Δ	
Soft jaws	•	•	•	•	•	•	•	•	•	•	•	•	
Dual pressure chucking	0	0	0	0	0	0	0	0	0	0	0		
Hydraulic chuck pressure switch	0	0	0	0	0	0	0	0	0	0	0	0	
Chuck clamp confirmation	0	0	0	0	0	0	0	0	0	0	0	0	
Tail stock center : Live center	•	•	×	X	•	×	•	•	•	X	×	×	
Tail stock center : Dead center	0	0	X	X	0	X	0	0	0	•	•	•	
Tail stock : Manual	•	•	×	X	•	×	•	•	•	X	×	×	
Tail stock : Programmable	0	0	X	X	0	X	0	0	0	•	•	•	
Tail stock : Servo driven	0	0	X	X	0	X	0	0	0	Х	X	X	
Automatic quill advance & retract	0	0	X	X	0	X	0	0	0	0	0	0	
Rotary tool holder	X	•	×	•	•	•	X	•	•	Х	•	•	
Tool setter : Manual	0	0	0	0	0	0	0	0	0	0	0	0	
Tool setter : Automatic_electric	0	0	0	0	0	0	0	0	0	0	0	0	
Auto workpiece measurement	0	0	0	0	0	0	0	0	0	0	0	0	
Linear scale (X-axis)	0	0	0	0	0	0	0	0	0	0	0	0	
Linear scale (Z-axis)	0	0	0	0	0	0	0	0	0	0	0	0	
Linear scale (Y-axis)	X	X	×	X	0	0	X	×	0	X	×	0	
Feedback system : Absolute position encoder	•	•	•	•	•	•	•	•	•	•	•	•	
Bar feeder interface	0	0	0	0	0	0	0	0	0	0	0	0	
Bar puller	Δ	Δ	Δ	Δ	Δ	Δ	Δ	Δ	Δ	X	×	X	
Workpiece ejector	X	X	0	0	×	0	X	X	×	Х	X	X	
Parts catcher with box	0	0	0	0	0	0	Δ	Δ	Δ	Х	×	X	
Parts catcher with conveyor	0	0	0	0	0	0	Δ	Δ	Δ	X	×	×	
Workpiece cut off confirmation	X	X	0	0	×	0	X	X	×	X	X	×	
Automatic front door: with safety device	0	0	0	0	0	0	0	0	0	0	0	0	
Chip conveyor type : Right side	0	0	0	0	0	0	0	0	0	0	0	0	
Chip conveyor type : Rear side *1	0	0	0	0	0	0	0	0	0	X	X	×	
Chip bucket	0	0	0	0	0	0	0	0	0	0	0	0	
TSC for main / left spindle	0	0	0	0	0	0	0	0	0	0	0	0	
Oil skimmer	0	0	0	0	0	0	0	0	0	0	0	0	
Coolant level switch	0	0	0	0	0	0	0	0	0	0	0	0	
Coolant chiller	0	0	0	0	0	0	0	0	0	0	0	0	
Oil mist collector	0	0	0	0	0	0	0	0	0	0	0	0	
Coolant blower	0	0	0	0	0	0	0	0	0	0	0	0	
Air blower	0	0	0	0	0	0	0	0	0	0	0	0	
Air gun	0	0	0	0	0	0	0	0	0	0	0	0	
Signal tower (yellow, red, green)	0	0	0	0	0	0	0	0	0	0	0	0	
Gantry loader	Δ	Δ	Δ	Δ	Δ	Δ	Δ	Δ	Δ	Δ	Δ	Δ	
V-stand for shaft workpiece	0	0	×	X	0	×	0	0	0	Х	X	X	

^{*1:} PUMA 2100/L, PUMA 2600, PUMA 3100 only

PUMA 3100XL / UL

○: option X: Not available

Steady	, Doct	PUMA	2100	PUMA	2600	PUMA	3100
Steau	/ Kest	Std.	L	Std.	L	Std./L	XL/UL
	Hydraulic	0	0	0	0	0	0
Type	Programmable	0	0	0	0	0	0
	Servo driven*1	X	X	X	X	X	0
	SLU-1	0	0	0	0	X	X
	SLU-2	0	0	0	0	0	0
	SLU-B3.1	X	0	0	0	X	X
Size	SLU-3.1	X	X	X	X	0	0
	SLU-3.2	X	X	X	X	X	0
	SLU-4	X	X	X	X	X	O *2
	SLU-B4	X	X	X	X	X	0

^{*1:} Rack & Pinion type. *2: SLU-4 is not available in servo driven type.

High pressure coolant

Model		PUMA 2100 /	2600 / 3100
Model		60Hz	50Hz
Standard	1.5 bar	0.4 kW x 0.15 MPa x 40 L/min (0.5 Hp x 21.8 psi x 10.6 galon/min)	0.4 kW x 0.15 MPa x 40 L/min (0.5 Hp x 21.8 psi x 10.6 galon/min)
	5 bar	0.9 kW x 0.45 MPa x 30 L/min (1.2 Hp x 65.3 psi x 7.9 galon/min)	0.9 kW x 0.30 MPa x 30 L/min (1.2 Hp x 43.5 psi x 7.9 galon/min)
	7 bar	1.5 kW x 0.7 MPa x 30 L/min (2.0 Hp x 101.5 psi x 7.9 galon/min)	1.5 kW x 0.5 MPa x 30 L/min (2.0 Hp x 72.5 psi x 7.9 galon/min)
option	10 bar*	2.2 kW x 1.0 MPa x 30 L/min (3.0 Hp x 145.0 psi x 7.9 galon/min)	2.2 kW x 0.7 MPa x 30 L/min (3.0 Hp x 101.5 psi x 7.9 galon/min)
	15 bar*	3.7 kW x 1.45 MPa x 30 L/min (5.0 Hp x 210.3 psi x 7.9 galon/min)	4.0 kW x 2.8 MPa x 20 L/min (5.0 Hp x 145.0 psi x 7.9 galon/min)
Special	28 bar*	4.0 kW x 2.8 MPa x 20 L/min (5.4 Hp x 406.6 psi x 5.3 galon/min)	4.0 kW x 1.95 MPa x 20 L/min (5.0 Hp x 282.8 psi x 5.3 galon/min)
option	70 bar*	5.5 kW x 7.0 MPa x 30 L/min (7.4 Hp x 1015.0 psi x 7.9 galon/min)	5.5 kW x 7.0 MPa x 26 L/min (7.4 Hp x 1015.0 psi x 6.9 galon/min)

^{*} Recommend using coolant chiller

Machine Specifications PUMA 2100 series

	Description	Unit	PUMA 2100/L	PUMA 2100M/LM	PUMA 2100MS/LMS	PUMA 2100S/LS			
	Swing over bed	mm (inch)		780	(30.7)				
	Swing over front door	mm (inch)		680	(26.8)				
	Swing over saddle	mm (inch)		630	(24.8)				
Capacity	Recom. Turning diameter	mm (inch)		210	(8.3)				
	Max. turning diameter	mm (inch)	480 (18.9)	406	(16.0)	480 (18.9)			
	Max. turning length	mm (inch)		520 / 760 (20.5 / 29.9)				
	Bar working diameter	mm (inch)		65	(2.6)				
	Travel distance X-axis	mm (inch)	260 [20+240] (10.2 [0.8+9.4])		7+203] .2+8.0])	260 [20+240] (10.2 [0.8+9.4])			
Travels	Z-axis	mm (inch)		590 / 830 (23.2 / 32.7)					
	Y-axis	mm (inch)							
	B-axis	mm (inch)	- 590 / 830 (23.2 / 32.7)						
	Rapid traverse X-axis	m/min (ipm)	30 (1181.1)						
	Z-axis	m/min (ipm)		30 (1	181.1)				
eedrates	Y-axis	m/min (ipm)		-					
	B-axis	m/min (ipm)		- 30 (1181.1)					
	Spindle speed (Belt Type)	r/min	4500						
	Spindle speed (Built-in Type)	r/min		-					
Main.	Spindle nose	,		A2#6					
Main Spindle	Spindle bearing diameter (Front)	mm (inch)			(4.7)				
	Spindle through hole diameter	mm (inch)			(3.0)				
	Min. spindle indexing angle (C-axis)	deg		70	0.001				
			12	12	[24]	12			
	No. of tool stations OD tool size		25 (1.0)			25 (1.0)			
		mm (inch)			1.0 [0.8])				
urret	Boring bar diameter	mm (inch)	50 (2.0)		1.6 [1.3])	50 (2.0)			
	Indexing time (1st swivel time)	S			15				
	Rotary tool spindle speed	r/min	-		000	•			
	Quill diameter	mm (inch)		(3.1)	-	•			
ail stock	Quill bore taper (Live)			T#4					
	Compressed air supply	mm (inch)	80	(3.1)	•				
	Spindle speed (Belt [Built-in])	r/min		-	4500				
	Spindle nose			-	ASA				
Sub-spindle	Spindle bearing diameter (Front)	mm (inch)		-	90 (
	Spindle through hole diameter	mm (inch)		-	62 (
	Min. spindle indexing angle (C-axis)	deg		-	0.0	01			
	Main spindle motor	kW (Hp)		18.5 / 15 (24.8 / 20.1)				
Motors	Sub spindle motor	kW (Hp)		-	7.5 / 5.5 (2	10.1 / 7.4)			
	Rotary tool spindle motor	kW (Hp)				-			
	Coolant pump motor	kW (Hp)	0.4 (0.5)						
Power source	Electric power supply (Rated capaci	y) kVA	4 35.63 38.41 45.63						
	Machine height	mm (inch)	1900 (74.8)						
	Machine dimension length	mm (inch)	3310 / 3530 (130.3 / 139.0)						
Machine size	width	mm (inch)	nch) 1863 (73.3)						
	Machine weight	kg (lb)	4850 / 5350 (10692.3 / 11794.6)	5000 / 5500 (11023.0 / 12125.2)	5450 / 5950 (12015.0 / 13117.3)	5300 / 5800 (11684.3 / 12786.			

[•] The specifications and information above-mentioned may be changed without prior notice.

[•] For more details, please contact Doosan

Machine Specifications PUMA 2100 / 2600 series

	Description	Unit	PUMA 2100Y/LY	P 2100SY/LSY	PUMA 2600/L	PUMA 2600M/LM	
	Swing over bed	mm (inch)		780	(30.7)		
	Swing over front door	mm (inch)		680	(26.8)		
	Swing over saddle	mm (inch)		630	(24.8)		
apacity	Recom. Turning diameter	mm (inch)	210	(8.3)	255 (10.0)		
	Max. turning diameter	mm (inch)	406	(16.0)	480 (18.9)	376 (14.8)	
	Max. turning length	mm (inch)	520 / 760 ((20.5 / 29.9)	760 / 1280 (29.9 / 50.4)		
	Bar working diameter	mm (inch)	65	(2.6)	76	(3.0)	
	Travel distance X-axi	s mm (inch)		7+203] 2.2+8.0])	260 [20+240] (10.2 [0.8+9.4])	260 [72+188] (10.2 [2.8+7.4])	
avels	Z-axi	s mm (inch)	590 / 830 ((23.2 / 32.7)	830 / 1350	(32.7 / 53.1)	
	Y-axi	s mm (inch)	105 [±52.5] (4.13 [±2.065])		-	
	B-axi	s mm (inch)	-	590 / 830 (23.2 / 32.7)		-	
	Rapid traverse X-axi	s m/min (ipm)		30 (1	181.1)		
	Z-axi	s m/min (ipm)		30 (1	181.1)		
edrates	Y-axi	-	10 (3	393.7)		-	
	B-axi		-	30 (1181.1)		-	
	Spindle speed (Belt Type)	r/min	45	500	31	500	
	Spindle speed(Built-in Type)	r/min		000		-	
4 - 5	Spindle nose			A2#6	ASA A2#8		
lain pindle	Spindle bearing diameter (Front)	mm (inch)		(4.7)	140 (5.5)		
	Spindle through hole diameter	mm (inch)		(3.0)		(3.4)	
	Min. spindle indexing angle (C-ax			001	-	0.001	
	No. of tool stations	st		4] [16]	12	12 [24]	
	OD tool size	mm (inch)		1.0 [0.8] [1.0])	25 (1.0)	25 [20] (1.0 [0.8])	
urret	Boring bar diameter	mm (inch)	40 [32] [32] (1.6 [1.3] [1.6])	50 (2.0)	50 [40] (2.0 [1.6])	
	Indexing time (1st swivel time)	S/:			.15		
	Rotary tool spindle speed	r/min		000	- 5000		
	Quill diameter	mm (inch)	80 (3.1)	-	100 (3.9)		
ail stock	Quill bore taper (Live)	0.13	MT#4	-		T#5	
	Quill travel	mm (inch)	80 (3.1)	-	100	(3.9)	
	Spindle speed (Belt [Built-in])	r/min	-	4500 [6000]		-	
	Spindle nose		-	ASA A2-5		-	
ub-spindle	Spindle bearing diameter (Front)	mm (inch)	-	90 (3.5)		-	
	Spindle through hole diameter	mm (inch)	-	62 (2.4)		-	
	Min. spindle indexing angle (C-ax	is) deg	-	0.001		-	
	Main spindle motor	kW (Hp)	18.5 / 15 (24.8 / 20.1)	22 / 18.5 (29.5 / 24.8)	
Notors	Sub spindle motor	kW (Hp)	-	7.5 / 5.5 (10.1 / 7.4)		-	
.5.015	Rotary tool spindle motor	kW (Hp)	5.5	(7.4)		-	
	Coolant pump motor	kW (Hp)	0.4		(0.5)		
ower ource	Electric power supply (Rated capa	acity) kVA	41.32	48.54	40.72	43.5	
	Machine height	mm (inch)	2163	(85.2)	1900	(74.8)	
	Machine dimension lengt	h mm (inch)	3310 / 3530 ((130.3 / 139.0)	3600 / 4335	(141.7 / 170.7)	
Machine size	width	n mm (inch)	1863	(73.3)	1863 / 1965	(73.3 / 77.4)	
	Machine weight	kg (lb)	5450 / 5950 (12015.0 / 13117.3)	5900 / 6400 (13007.1 / 14109.4)	5400 / 6700 (11904.8 / 14770.8)	5550 / 6850 (12235.5 / 15101.4	

[•] The specifications and information above-mentioned may be changed without prior notice.

[•] For more details, please contact Doosan

Machine Specifications PUMA 2600 series

	Description	Unit	PUMA 2600MS/LMS	PUMA 2600S/LS	PUMA 2600Y/LY	PUMA 2600SY/LSY	
	Swing over bed	mm (inch)		780 (30.7)		
	Swing over front door	mm (inch)		680 (26.8)		
	Swing over saddle	mm (inch)		630 (24.8)		
Capacity	Recom. Turning diameter	mm (inch)		255 (10.0)		
	Max. turning diameter	mm (inch)	376 (14.8)	480 (18.9)	376	(14.8)	
	Max. turning length	mm (inch)		760 / 1280	(29.9 / 50.4)		
	Bar working diameter	mm (inch)		76 (3.0)		
	Travel distance X-axis	mm (inch)	260 [72+188] (10.2 [2.8+7.4])	260 [20+240] (10.2 [0.8+9.4])	260 [72+188] (10.2 [2.8+7.4])		
ravels -	Z-axis	mm (inch)		830 / 1350	(32.7 / 53.1)		
	Y-axis	mm (inch)		-	105 [±52.5] (4.13 [±2.065])	
	B-axis	mm (inch)	830/1350	(32.7/53.1)	-	830/1350 (32.7/53.1	
	Rapid traverse X-axis	m/min (ipm)		30 (1:	181.1)		
	Z-axis	m/min (ipm)		30 (1:	181.1)		
eedrates	Y-axis	m/min (ipm)		-	10 (3	93.7)	
	B-axis	m/min (ipm)	30 (1:	181.1)	-	30 (1181.1)	
	Spindle speed (Belt Type)	r/min		35	00		
	Spindle speed (Built-in)	,				000	
4 1	Spindle nose			ASA			
Main Spindle	Spindle bearing diameter (Front)	mm (inch)		140			
	Spindle through hole diameter	mm (inch)		86 (
	Min. spindle indexing angle (C-axis		0.001			001	
	No. of tool stations	st	12 [24]	12		4] [16]	
	OD tool size	mm (inch)	25 [20] (1.0 [0.8])	25 (1.0)		1.0 [0.8] [1.0])	
		mm (inch)					
urret	Boring bar diameter Indexing time (1st swivel time)		50 [40] (2.0 [1.6]) 50 (2.0) 40 [32] [32] (1.0 [1.7] [1.0])	
		5	5000				
	Rotary tool spindle speed	r/min	5000	-	5000		
	Quill diameter	mm (inch)		-	100 (3.9)	-	
ail stock	Quill bore taper (Live)	0.13		-	MT#5	-	
	Quill travel	mm (inch)			100 (3.9)	-	
	Spindle speed (Belt [Built-in])	r/min		0[-]	-	4500 [6000]	
	Spindle nose			A2-5	-	ASA A2-5	
ub-spindle	Spindle bearing diameter (Front)	mm (inch)		(3.5)	-	90 (3.5)	
	Spindle through hole diameter	mm (inch)		(2.4)	-	62 (2.4)	
	Min. spindle indexing angle (C-axis)	deg	0.0	001	-	0.001	
	Main spindle motor	kW (Hp)		22 / 18.5 (2	29.5 / 24.8)		
Notors	Sub spindle motor	kW (Hp)	7.5 / 5.5 (10.1 / 7.4)	-	7.5 / 5.5 (10.1 / 7.4)	
	Rotary tool spindle motor	kW (Hp)	5.5 [7.5] (7.4 [10.1])	-	5.5 [7.5] (7.4 [10.1])	
	Coolant pump motor	kW (Hp)		0.4	(0.5)		
ower ource	Electric power supply (Rated capaci	ty) kVA	51.65	48.86	46.4	54.55	
	Machine height	mm (inch)	1900	(74.8)	2163	(85.2)	
	Machine dimension length	mm (inch)	3600 / 4335 (141.7 / 170.7)	3600 / 4435 ((141.7 / 174.6)	
Machine size	width	mm (inch)		1863 / 1965	(73.3 / 77.4)		
	Machine weight	kg (lb)	6000 / 7300 (13227.5 / 16093.5)	5850 / 7150 (12896.9 / 15762.8)	6000 / 7300 (13227.5 / 16093.5)	6450 / 7750 (14219.6 / 17085.6)	

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[•] For more details, please contact Doosan

Machine Specifications PUMA 2600 series

	Description		Unit	PUMA 2600/500	PUMA 2600M/500	PUMA 2600B/LB	PUMA 2600MB/LMB				
	Swing over bed		mm (inch)		780	(30.7)					
	Swing over front door		mm (inch)		680	(26.8)					
	Swing over saddle		mm (inch)		630	(24.8)					
Capacity	Recom. Turning diameter		mm (inch)	255	(10.0)	305	(12.0)				
	Max. turning diameter		mm (inch)	480 (18.9)	376 (14.8)	480 (18.9)	376 (14.8)				
	Max. turning length		mm (inch)	520	(20.5)	725 [1245]	(28.5 [49.0])				
	Bar working diameter		mm (inch)	65	(2.6)	102	2 (4.0)				
	Travel distance	X-axis	mm (inch)	260 [20+240] (10.2 [0.8+9.4])	260 [72+188] (10.2 [2.8+7.4])	260 [20+240] (10.2 [0.8+9.4])	260 [72+188] (10.2 [2.8+7.4])				
ravels	_	Z-axis	mm (inch)	590	(23.2)	830[1350]	(32.7[53.1])				
		Y-axis	mm (inch)								
		B-axis	mm (inch)	·							
	Rapid traverse	X-axis	m/min (ipm)		30 (1	181.1)					
		Z-axis	m/min (ipm)	30 (1181.1)							
eedrates	-	Y-axis	m/min (ipm)			-					
	_	B-axis	m/min (ipm)		-						
	Spindle speed (Belt Type)		r/min	3500	(137.8)	2800	(110.2)				
	Spindle nose			ASA	A2-8	A	2-11				
lain nindla	Spindle bearing diameter (F	ront)	mm (inch)	140	(5.5)	160 (6.3)					
oindle	Spindle through hole diame	ter	mm (inch)	86	(3.4)	115	5 (4.5)				
	Min. spindle indexing angle	(C-axis)	deg		0.0	001					
	No. of tool stations		st	12	12 [24]	12	12 [24]				
	OD tool size		mm (inch)	25 (1.0)	25 [20] (1.0 [0.8])	25 (1.0)	25 [20] (1.0 [0.8])				
ırret	Boring bar diameter		mm (inch)	50 (2.0)	50 [40] (2.0 [1.6])	50 (2.0)	50 [40] (2.0 [1.6])				
	Indexing time (1st swivel tim	ne)	S		0.	15					
	Rotary tool spindle speed		r/min	-	5000	-	5000				
	Quill diameter		mm (inch)		100	(3.9)					
ail stock	Quill bore taper (Live)				M	[#5					
	Quill travel		mm (inch)		100	(3.9)					
	Spindle speed (Belt [Built-in	1)	r/min			-					
	Spindle nose	2				-					
ub-spindle	Spindle bearing diameter (Fi	ront)	mm (inch)			-					
	Spindle through hole diame		mm (inch)			-					
	Min. spindle indexing angle		deg			-					
	Main spindle motor	, ,	kW (Hp)	18.5/15 (24.8/20.1)	22/18.5	(29.5/24.8)				
	Sub spindle motor		kW (Hp)			-	, ,				
Notors	Rotary tool spindle motor		kW (Hp)	-	5.5 (7.4)	-	5.5 (7.4)				
	Coolant pump motor		kW (Hp)			(0.5)					
ower	Electric power supply (Rated	l capacity)	kVA	40.72	44.42	40.72	44.42				
source	Machina haight		mm (inch)		1000	(74.8)					
	Machine height Machine dimension	longth	mm (inch)	2270			(1 / F 7 [1 7 / 7])				
Machine size	_	length	mm (inch)	33/0	(132.7)		(145.7 [174.7])				
Machine size	Machine weight	width	mm (inch)	4900 (10802.5)	5000 (11023.0)	(73.3) 5500 [6800] (12125.2 [14991.2])	5650 [6950] (12455.9 [15321.9])				

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[•] For more details, please contact Doosan

Machine Specifications PUMA 2600 series

	Description		Unit	PUMA 2600SB	PUMA 2600MSB	PUMA 2600YB	PUMA 2600SYB			
	Swing over bed		mm (inch)		780 (30.7)				
	Swing over front door		mm (inch)		680 (26.8)				
	Swing over saddle		mm (inch)		630 (24.8)				
apacity	Recom. Turning diameter		mm (inch)		305 (12.0)				
	Max. turning diameter		mm (inch)	480 (18.9)		376 (14.8)				
	Max. turning length		mm (inch)		725 (28.5)				
	Bar working diameter		mm (inch)		102	(4.0)				
	Travel Travel distance	X-axis	mm (inch)	260 (10.2)	20+240 (0.8+9.4)	(10.2)				
		Z-axis	mm (inch)		830 (32.7)					
avels		Y-axis	mm (inch)		-	10	5 (4.1)			
		B-axis	mm (inch)	830 (0 (32.7) - 83					
	Rapid traverse	X-axis	m/min (ipm)		30 (1181.1)					
		Z-axis	m/min (ipm)		30 (11	.81.1)				
edrates		Y-axis	m/min (ipm)		-	10 (
		B-axis	m/min (ipm)	30 (1:	.181.1) - 30 (1181.1					
	Spindle speed (Belt Type)		r/min		2800 (110.2)				
	Spindle nose			ASA A2-11						
ain	Spindle bearing diameter	(Front)	mm (inch)		160	(6.3)				
oindle	Spindle through hole dia	meter	mm (inch)		115	(4.5)				
	Min. spindle indexing an		deg	-		0.001				
	No. of tool stations		st	12		12 [24]				
	OD tool size		mm (inch)	25 (1.0) 25 [20] (1.0 [0.8])						
ırret	Boring bar diameter		mm (inch)	50 (2.0)						
	Indexing time (1st swivel	time)	S		0.:	15				
	Rotary tool spindle speed		r/min	-		5000				
	Quill diameter		mm (inch)	100 (3.9)						
il stock	Quill bore taper (Live)				MT#5					
	Quill travel		mm (inch)		100	(3.9)				
	Spindle speed (Belt [Built	:-in])	r/min	4500 ((177.2)	-	4500 (177.2)			
	Spindle nose				A2#5	-	ASA A2#5			
ub-spindle	Spindle bearing diameter	(Front)	mm (inch)	90 ((3.5)	-	90 (3.5)			
	Spindle through hole dia	meter	mm (inch)	62 ((2.4)	-	62 (2.4)			
	Min. spindle indexing an	gle (C-axis)	deg	0.0	001		0.001			
	Main spindle motor		kW (Hp)		22/18.5 (2	29.5/24.8)				
	Sub spindle motor		kW (Hp)	7.5/5.5 (10.1/7.4)	-	7.5/5.5 (10.1/7.4)			
otors	Rotary tool spindle motor		kW (Hp)	- 5.5 (7.4)						
	Coolant pump motor		kW (Hp)	0.4 (0.5)						
ower source	Electric power supply (Ra	ted capacity)	kVA	48	.86	46.40	54.55			
	Machine height	. "	mm (inch)							
	Machine dimension	length	mm (inch)		3700 (,			
Nachine size		width	mm (inch)		1863					
	Machine weight		kg (lb)	5950 (13117.3)	6100 (13448.0)	6100 (13448.0)	6550 (14440.1)			

[•] The specifications and information above-mentioned may be changed without prior notice.

[•] For more details, please contact Doosan

Machine Specifications PUMA 3100 series

	Description		Unit	PUMA 3100/L/XL/UL	PUMA 3100M/LM/XLM/ULM	PUMA 3100Y/LY/XLY/ULY	
	Swing over bed		mm (inch)		850 (33.5)		
	Swing over front door		mm (inch)	720 (28.3)* / 850 (33.5)**			
Capacity	Swing over saddle		mm (inch)		670 (26.4)		
	Recom. Turning diameter		mm (inch)	305 (12.0)			
	Max. turning diameter		mm (inch)	525 (20.7) 420 (16.5)			
	Max. turning length		mm (inch)	760 / 1280 / 2125 / 3125 (29.9 / 50.4 / 83.7 / 123.0)			
	Bar working diameter		mm (inch)	102 (4.0)			
	Travel distance X-axis		mm (inch)	293 [30.5+262.5] (11.5 [1.2+10.3]) 293 [83+210] (11.5 [3.3+8.3])			
Travels		Z-axis	mm (inch)	830 / 1350 / 2190 / 3190(32.7 / 53.1 / 86.2 / 125.6)			
		Y-axis	mm (inch)		-	130 [±65] (5.1 [±2.6])	
		B-axis	mm (inch)		-		
	Rapid traverse X-axis		m/min (ipm)		30 (1181.1)		
	'	Z-axis	m/min (ipm)	30 / 30 / 30 / 26 (1181.1 / 1181.1 / 1023.6)			
eedrates		Y-axis	m/min (ipm)		-	10 (393.7)	
	B-axis		m/min (ipm)		-		
	Spindle speed (Belt Type))	r/min		2800		
	Spindle speed (Built-in Type)		r/min	3000			
ain	Spindle nose			ASA A2#11			
oindle	Spindle bearing diameter	r (Front)	mm (inch)	160 (6.3)			
	Spindle through hole diameter		mm (inch)	115 (4.5)			
	Min. spindle indexing angle (C-axis)		deg	0.001			
	No. of tool stations		st	10 12			
	OD tool size		mm (inch)	25 (1.0)			
rret	Boring bar diameter		mm (inch)	50 (2.0)			
	Indexing time (1st swivel time)		S	0.15			
	Rotary tool spindle speed		r/min	- 5000			
	Quill diameter		mm (inch)	100 / 100 / 120 / 120 (3.9 / 3.9 / 4.7 / 4.7)			
ail stock	Quill bore taper (Live)			MT#5			
	Ouill travel		mm (inch))	
	Spindle speed (Belt [Built-in])		r/min		-		
	Spindle nose				-		
ub-spindle	Spindle bearing diameter (Front)		mm (inch)				
p	Spindle through hole diameter		mm (inch)				
	Min. spindle indexing angle (C-axis)		deg	•			
	Main spindle motor		kW (Hp)	22 / 18.5 (29.5 / 24.8)			
	Sub spindle motor		kW (Hp)				
otors	Rotary tool spindle motor		kW (Hp)	5.5 [7.5] (7.4 [10.1])			
	Coolant pump motor		kW (Hp)	0.4 (0.5)			
ower source	Electric power supply (Ra	ted capacity)	kVA	41.64 / 41.64 / 42.83 / 42.83	44.42 / 44.42 / 45.61 / 45.61	46.40 / 46.40 / 47.59 / 47.59	
	Machine height		mm (inch)		15 (79.5 / 79.5 / 91.1 / 91.1)	2315 (91.1)	
	Machine dimension length width Machine weight		mm (inch)		4530 / 5615 / 5685 (153.9 / 178.3 / 221.1	, ,	
lachine size			mm (inch)		2 / 2105 / 2280 / 2280 (78.8 / 82.9 / 89.8 /		
			kg (lb)	5850/ 7350 / 10150 / 11650	6000 / 7500 / 10300 / 11800) (13227.5 / 16534.4/22707.3 / 26014.4)	6500 / 8000 / 10800 / 12300	

Standard feature

- Hydraulic power unit
- Lubrication equipment
- Coolant supply equipment
- Front guard door interlock
- Hydraulic chuck & actuating cylinder
- Soft jaws
- Foot switch
- Standard tool kit (tool holder & boring sleeve)
- Work light
- Manuals
- Levelling jack screw & plates
- Hand tool kit (including small tool for operations)
- Safety precaution name plates

Optional feature

- Additional tool holder & sleeves
- Air blast for chuck jaw cleaning
- Air gun
- Automatic door with safety device
- Bar feeder interface
- Dual chucking pressure
- Hardened & ground jaws
- Pressure switch for chucking pressure check
- High pressure coolant
- Oil skimmer
- Chip conveyor

- Chip bucket
- Programmable tail stock
- Servo driven tail stock
- Signal tower (yellow, red, green)
- Tail stock quill for dead center
- Tool pre-setter (Automatic type)
- Tool pre-setter (Manual type)
- Work ejector
- Parts catcher
- Parts conveyor
- Controller : Fanuc 31i
- The specifications and information above-mentioned may be changed without prior notice.
- \bullet For more details, please contact Doosan

NC Unit Specifications

Fanuc 31i

	- Spindle Output switching
- Controlled axes X, Z, C, Y [C2, B]	
- Simultaneous controlled axes 4 axes	PROGRAM INPUT
- Angular axis control	- Absolute / incremental program
- Axis control by PMC	- Addition of custom macro com
- Backlash compensation 0 ~ ±9999 pulses	Automotic coordinate quatern o
- Backlash compensation for each rapid traverse and cutting feed	- Automatic coordinate system so
- Chamfering on / off - Cs contouring control	- Canned cycle for drilling / Turning - Canned cycle
- HRV2 control	- Circular interpolation by R progr
- Least input command 0.001 / 0.0001 mm/inch	- Control in/out
- Machine lock All axis / each axis	- Coordinate system setting
- Mirror image	- Coordinate system shift
- Overtravel	- Custom macro
- Position switch	- Decimal point programming / P
- Stored pitch error compensation	point programming
- Stored stroke check 1	 Diameter/radius programming Direct drawing dimension programming
- Torque control	- Direct input of coordinate syste
- Interference chek for rotary area - Unexpected disturbance torque detection function	- G code system A
- onexpected disturbance torque detection function	- G code system B/C
OPERATION	- Input unit 10 time multiply
- Automatic operation (memory)	- Label skip
- MDI operation	- Macro executor
- DNC Operation with Memory card	- Manual absolute on and off
- Buffer register	- Maximum program dimension
- Dry run	Multiple repetitive canned cycle Multiple repetitive canned cycle
- Handle incremental feed X1, X10, X100	 Multiple repetitive canned cycle Optional block skip
- Program restart	- Parity check
- Wrong operation prevention	- Plane selection
- JOG feed - Manual handle feed 1unit	- Program file name
- Manual intervention and return	- Program stop / end(M00, M01
- Manual pulse generator 1 ea	- Programmable data input
- Manual reference position return	- Sequence number
- Program number search	- SUB program call
- Refernce position setting without dog	- Tape code : ISO / EIA auto recog
- Sequence number search	Ton a format for FANILIC Corines I
- Single block	 Tape format for FANUC Series 15 Work coordinate system
INTERPOLATION FUNCTIONS	- Work coordinate system
- Nano interpolation	TOOL FUNCTION / TOOL COMPEN
- Positioning G00	- Automatic tool offset
- 1st. Reference position return Manual, G28	- Direct input of offset value mea
- 2nd. reference position return G30	- Direct input of offset value mea
- Circular interpolation G02	- T-code function
- Continuous threading	- Tool geometry / wear compensa
- Cylindrical interpolation	- Tool life management
- Dwell (per sec) G04	- Tool Load Monitoring system *
- Linear interpolation G01	- Tool nose radius compensation - Tool offset
- Multiple threading	- Tool offset pairs
- Polar coordinate interpolation	
	- 1001 offset value counter input
- Helical interpolation	- Tool offset value counter input - Y-axis offset
- Helical interpolation - Reference position return check G27	
- Helical interpolation - Reference position return check G27 - Skip G31	
- Helical interpolation 627 - Reference position return check 627 - Skip 631 - Thread cutting / Synchronous cutting	- Y-axis offset EDITING OPERATION - Back ground editting
- Helical interpolation 627 - Reference position return check 627 - Skip 631 - Thread cutting / Synchronous cutting	- Y-axis offset EDITING OPERATION - Back ground editting - Extended part program editing
- Helical interpolation - Reference position return check - Skip - Skip - Thread cutting / Synchronous cutting - Thread cutting retract - Torque limit skip	- Y-axis offset EDITING OPERATION - Back ground editting - Extended part program editing - Memory card edit & operation
- Helical interpolation - Reference position return check - Skip - Skip - Thread cutting / Synchronous cutting - Thread cutting retract - Torque limit skip FEED FUNCTION	- Y-axis offset EDITING OPERATION - Back ground editting - Extended part program editing - Memory card edit & operation - Number of registered programs
- Helical interpolation - Reference position return check - Skip - Skip - Thread cutting / Synchronous cutting - Thread cutting retract - Torque limit skip - FEED FUNCTION - Automatic acceleration / deceleration	- Y-axis offset EDITING OPERATION - Back ground editting - Extended part program editing - Memory card edit & operation - Number of registered programs - Part program editing
- Helical interpolation Reference position return check - Skip G31 - Thread cutting / Synchronous cutting - Thread cutting retract - Torque limit skip FEED FUNCTION - Automatic acceleration / deceleration - Cutting feedrate clamp	- Y-axis offset EDITING OPERATION - Back ground editting - Extended part program editing - Memory card edit & operation - Number of registered programs - Part program editing - Part program storage size
- Helical interpolation - Reference position return check - Reference position return check - Skip - Skip - G31 - Thread cutting / Synchronous cutting - Thread cutting retract - Torque limit skip - Teppe limit skip - FEED FUNCTION - Automatic acceleration / deceleration - Cutting feedrate clamp - Feed per minute	- Y-axis offset EDITING OPERATION - Back ground editting - Extended part program editing - Memory card edit & operation - Number of registered programs - Part program editing
- Helical interpolation - Reference position return check - Reference position return check - Skip - G31 - Thread cutting / Synchronous cutting - Thread cutting retract - Torque limit skip FEED FUNCTION - Automatic acceleration / deceleration - Cutting feedrate clamp - Feed per minute - Feed per revolution	- Y-axis offset EDITING OPERATION - Back ground editting - Extended part program editing - Memory card edit & operation - Number of registered programs - Part program editing - Part program storage size - Program protect
- Helical interpolation - Reference position return check - Skip - G31 - Thread cutting / Synchronous cutting - Thread cutting retract - Torque limit skip - EED FUNCTION - Automatic acceleration / deceleration - Cutting feedrate clamp - Feed per minute - Feed per revolution - Feed revolution - Feedrate override (10% unit) - O - 200 %	- Y-axis offset EDITING OPERATION - Back ground editting - Extended part program editing - Memory card edit & operation - Number of registered programs - Part program editing - Part program storage size
- Helical interpolation - Reference position return check - Skip - G31 - Thread cutting / Synchronous cutting - Thread cutting retract - Torque limit skip - FEED FUNCTION - Automatic acceleration / deceleration - Cutting feedrate clamp - Feed per minute - Feed per revolution - Feed ret override (10% unit) - Jog feed override (10% unit) - 0 - 2000 mm/min	- Y-axis offset EDITING OPERATION - Back ground editting - Extended part program editing - Memory card edit & operation - Number of registered programs - Part program editing - Part program storage size - Program protect SETTING AND DISPLAY - Actual cutting feedrate display - Alarm display
- Helical interpolation - Reference position return check - Reference position return check - Reference position return check - Skip - G31 - Thread cutting / Synchronous cutting - Thread cutting retract - Torque limit skip - Torque limit skip - FEED FUNCTION - Autromatic acceleration / deceleration - Cutting feedrate clamp - Feed per minute - Feed per revolution - Feed per revolution - Feed do verride (10% unit) - Jog feed override (10% unit) - Manual per revolution feed	- Y-axis offset EDITING OPERATION - Back ground editting - Extended part program editing - Memory card edit & operation - Number of registered programs - Part program editing - Part program storage size - Program protect SETTING AND DISPLAY - Actual cutting feedrate display - Alarm display - Alarm history display
- Helical interpolation - Reference position return check - Reference position return check - Skip - G31 - Thread cutting / Synchronous cutting - Thread cutting retract - Torque limit skip - FEED FUNCTION - Automatic acceleration / deceleration - Cutting feedrate clamp - Feed per minute - Feed per revolution - Feed revolution - Feed revolution - Feed override (10% unit) - Jog feed override (10% unit) - Manual per revolution feed - Override cancel - Rapid traverse override - F0, 25, 100 %	- Y-axis offset EDITING OPERATION - Back ground editting - Extended part program editing - Memory card edit & operation - Number of registered programs - Part program editing - Part program storage size - Program protect SETTING AND DISPLAY - Actual cutting feedrate display - Alarm history display - Current position display
- Helical interpolation - Reference position return check - Reference position return check - Skip - G31 - Thread cutting / Synchronous cutting - Thread cutting retract - Torque limit skip - Thread cutting retract - Torque limit skip - FEED FUNCTION - Automatic acceleration / deceleration - Cutting feedrate clamp - Feed per minute - Feed per revolution - Feed per revolution - Feed ger revolution - Jog feed override (10% unit) - Jog feed override (10% unit) - Manual per revolution feed - Override cancel	- Y-axis offset EDITING OPERATION - Back ground editting - Extended part program editing - Memory card edit & operation - Number of registered programs - Part program editing - Part program storage size - Program protect SETTING AND DISPLAY - Actual cutting feedrate display - Alarm display - Alarm history display - Current position display - Periodic maintenance screen
- Helical interpolation - Reference position return check - Reference position return check - Reference position return check - Skip - G31 - Thread cutting / Synchronous cutting - Thread cutting retract - Torque limit skip - Torque limit skip - FEED FUNCTION - Automatic acceleration / deceleration - Cutting feedrate clamp - Feed per minute - Feed per revolution - Feed per revolution - Feed do verride (10% unit) - Jog feed override (10% unit) - Manual per revolution feed - Override cancel - Rapid traverse override - Rapid traverse override - Tangential speed constant control	- Y-axis offset EDITING OPERATION - Back ground editting - Extended part program editing - Extended part program editing - Memory card edit & operation - Number of registered programs - Part program storage size - Program protect SETTING AND DISPLAY - Actual cutting feedrate display - Alarm display - Alarm history display - Current position display - Periodic maintenance screen - Display of spindle speed and T
- Helical interpolation - Reference position return check - Skip - G31 - Thread cutting / Synchronous cutting - Thread cutting retract - Torque limit skip - Torque limit skip - FEED FUNCTION - Automatic acceleration / deceleration - Cutting feedrate clamp - Feed per minute - Feed per revolution - Feed per revolution - Feed override (10% unit) - Jog feed override (10% unit) - Jog feed override (10% unit) - O - 2000 mm/min - Manual per revolution feed - Override cancel - Rapid traverse override - Tangential speed constant control AUXILIARY / SPINDLE SPEED FUNCTION	- Y-axis offset EDITING OPERATION - Back ground editting - Extended part program editing - Memory card edit & operation - Number of registered programs - Part program editing - Part program storage size - Program protect SETTING AND DISPLAY - Actual cutting feedrate display - Alarm display - Alarm history display - Current position display - Periodic maintenance screen - Display of spindle speed and T - Help function
- Helical interpolation - Reference position return check - Skip - G31 - Thread cutting / Synchronous cutting - Thread cutting retract - Torque limit skip - FEED FUNCTION - Automatic acceleration / deceleration - Cutting feedrate clamp - Feed per minute - Feed per minute - Feed per revolution - Feedrate override (10% unit) - Jog feed override (10% unit) - Manual per revolution feed - Override cancel - Rapid traverse override - Rapid traverse override - Tangential speed constant control - Spindle orientation	- Y-axis offset EDITING OPERATION - Back ground editting - Extended part program editing - Memory card edit & operation - Number of registered programs - Part program editing - Part program storage size - Program protect SETTING AND DISPLAY - Actual cutting feedrate display - Alarm history display - Current position display - Periodic maintenance screen - Display of spindle speed and T - Help function - Multi-language display
- Helical interpolation - Reference position return check - Reference position return check - Reference position return check - Skip - G31 - Thread cutting / Synchronous cutting - Thread cutting retract - Torque limit skip - FEED FUNCTION - Automatic acceleration / deceleration - Cutting feedrate clamp - Feed per minute - Feed per revolution - Feed per revolution - Feedrate override (10% unit) - Jog feed override (10% unit) - Jog feed override (10% unit) - Annual per revolution feed - Override cancel - Rapid traverse override - Tangential speed constant control AUXILIARY / SPINDLE SPEED FUNCTION - Spindle orientation - Actual spindle speed output	- Y-axis offset EDITING OPERATION - Back ground editting - Extended part program editing - Extended part program editing - Memory card edit & operation - Number of registered programs - Part program editing - Part program storage size - Program proteor - Program proteor - Program proteor - Program fisplay - Actual cutting feedrate display - Alarm display - Current position display - Current position display - Periodic maintenance screen - Display of spindle speed and T - Help function - Multi-language display - Operation history display
- Helical interpolation - Reference position return check - Skip - G31 - Thread cutting / Synchronous cutting - Thread cutting retract - Torque limit skip - FEED FUNCTION - Automatic acceleration / deceleration - Cutting feedrate clamp - Feed per minute - Feed per revolution - Feed per revolution - Feed per revolution - Feed override (10% unit) - Jog feed override (10% unit) - Manual per revolution feed - Override cancel - Rapid traverse override - Tangential speed constant control AUXILIARY / SPINDLE SPEED FUNCTION - Spindle orientation - Actual spindle speed output - Auxiliary function lock	- Y-axis offset EDITING OPERATION - Back ground editting - Extended part program editing - Memory card edit & operation - Number of registered programs - Part program storage size - Program protect SETTING AND DISPLAY - Actual cutting feedrate display - Alarm history display - Current position display - Urrent position display - Periodic maintenance screen - Display of spindle speed and T - Help function - Multi-language display - Operation history display - Parameter setting and display
- Helical interpolation - Reference position return check - Reference position return check - Skip - Reference position return check - Skip - G31 - Thread cutting / Synchronous cutting - Thread cutting retract - Torque limit skip - FEED FUNCTION - Automatic acceleration / deceleration - Cutting feedrate clamp - Feed per minute - Feed per revolution - Feed per revolution - Feed per revolution - Feed ger evolution - Feed ed override (10% unit) - Jog feed override (10% unit) - O - 2000 mm/min - Manual per revolution feed - Override cancel - Rapid traverse override - Tangential speed constant control AUXILIARY / SPINDLE SPEED FUNCTION - Spindle orientation - Actual spindle speed output - Auxiliary function lock - Constant surface speed control	- Y-axis offset EDITING OPERATION - Back ground editting - Extended part program editing - Extended part program editing - Memory card edit & operation - Number of registered programs - Part program editing - Part program storage size - Program protect - Program protect - Program protect - Program fisplay - Alarm display - Alarm history display - Current position display - Periodic maintenance screen - Display of spindle speed and T - Help function - Multi-language display - Operation history display
- Helical interpolation - Reference position return check - Skip - G31 - Thread cutting / Synchronous cutting - Thread cutting retract - Torque limit skip - Torque limit skip - FEED FUNCTION - Automatic acceleration / deceleration - Cutting feedrate clamp - Feed per minute - Feed per revolution - Feed per revolution - Feed per revolution - Jog feed override (10% unit) - Jog feed override (10% unit) - O - 2000 mm/min - Manual per revolution feed - Override cancel - Rapid traverse override - Tangential speed constant control - Tangential speed constant control - AUXILIARY / SPINDLE SPEED FUNCTION - Spindle orientation - Actual spindle speed output - Auxiliary function lock - Constant surface speed control - M-code function M3 digits - M3 digits	- Y-axis offset EDITING OPERATION - Back ground editting - Extended part program editing - Memory card edit & operation - Number of registered programs - Part program editing - Part program storage size - Program protect SETTING AND DISPLAY - Actual cutting feedrate display - Alarm display - Current position display - Periodic maintenance screen - Display of spindle speed and T - Help function - Multi-language display - Operation history display - Pogram comment display
- Helical interpolation - Reference position return check - Skip - Thread cutting / Synchronous cutting - Thread cutting retract - Torque limit skip - Torque limit skip - FEED FUNCTION - Automatic acceleration / deceleration - Cutting feedrate clamp - Feed per minute - Feed per revolution - Feed per revolution - Feed acceleration / O-200 mm/min - Manual per revolution feed - Override cancel - Rapid traverse override - Rapid traverse override - Tangential speed constant control - AUXILIARY / SPINDLE SPEED FUNCTION - Spindle orientation - Actual spindle speed output - Auxiliary function lock - Constant surface speed control - M-code function M3 digits - Multi spindle control	- Y-axis offset EDITING OPERATION - Back ground editting - Extended part program editing - Memory card edit & operation - Number of registered programs - Part program editing - Part program storage size - Program protect SETTING AND DISPLAY - Actual cutting feedrate display - Alarm display - Alarm display - Current position display - Periodic maintenance screen - Display of spindle speed and T - Help function - Multi-language display - Parameter setting and display - Program comment display - Run hours / part count display - Run hours / part count display - Self-diagnosis function - Servo setting screen
- Helical interpolation - Reference position return check - Skip - Thread cutting / Synchronous cutting - Thread cutting retract - Torque limit skip - Terque limit skip - Return cacceleration / deceleration - Automatic acceleration / deceleration - Cutting feedrate clamp - Feed per minute - Feed per revolution - Feed per revolution - Feed per revolution - Jog feed override (10% unit) - Jog feed override (10% unit) - O - 2000 mm/min - Manual per revolution feed - Override cancel - Rapid traverse override - Tangential speed constant control AUXILIARY / SPINDLE SPEED FUNCTION - Spindle orientation - Actual spindle speed output - Auxiliary function lock - Constant surface speed control - M-code function M3 digits - M3 digits	- Y-axis offset EDITING OPERATION - Back ground editting - Extended part program editing - Memory card edit & operation - Mumber of registered programs - Part program editing - Part program editing - Part program storage size - Program protect SETTING AND DISPLAY - Actual cutting feedrate display - Alarm display - Current position display - Periodic maintenance screen - Display of spindle speed and T - Help function - Multi-language display - Operation history display - Parameter setting and display - Program comment display - Run hours / part count display - Self-diagnosis function - Servo setting screen - Spindle setting screen
- Helical interpolation - Reference position return check - Reference position return check - Reference position return check - Skip - G31 - Thread cutting / Synchronous cutting - Thread cutting retract - Torque limit skip - FEED FUNCTION - Automatic acceleration / deceleration - Cutting feedrate clamp - Feed per minute - Feed per revolution - Feed per revolution - Feed per revolution - Feed override (10% unit) - Manual per revolution feed - Override cancel - Rapid traverse override - Tangential speed constant control AUXILIARY / SPINDLE SPEED FUNCTION - Spindle orientation - Actual spindle speed output - Auxillary function lock - Constant surface speed control - M-code function M3 digits - Multi spindle control - Rigid tapping	- Y-axis offset EDITING OPERATION - Back ground editting - Extended part program editing - Extended part program editing - Memory card edit & operation - Number of registered programs - Part program storage size - Program protect SETTING AND DISPLAY - Actual cutting feedrate display - Alarm display - Alarm history display - Current position display - Periodic maintenance screen - Display of spindle speed and T - Help function - Multi-language display - Operation history display - Parameter setting and display - Program comment display - Program comment display - Self-diagnosis function - Servo setting screen - Spindle setting screen - Status display
- Helical interpolation - Reference position return check - Reference position return check - Skip - Thread cutting / Synchronous cutting - Thread cutting retract - Torque limit skip - Teta cutting retract - Torque limit skip - Reference position / deceleration - Automatic acceleration / deceleration - Cutting feedrate clamp - Feed per minute - Feed per revolution - Feed per revolution - Feedrate override (10% unit) - Jog feed override (10% unit) - O - 2000 mm/min - Manual per revolution feed - Override cancel - Rapid traverse override - Tangential speed constant control AUXILIARY / SPINDLE SPEED FUNCTION - Spindle orientation - Actual spindle speed output - Auxiliary function lock - Constant surface speed control - Mcode function M3 digits - Multi spindle control - Rigid tapping - S-code function - S4 / S5 digits	- Y-axis offset EDITING OPERATION - Back ground editting - Extended part program editing - Memory card edit & operation - Mumber of registered programs - Part program editing - Part program editing - Part program storage size - Program protect SETTING AND DISPLAY - Actual cutting feedrate display - Alarm display - Current position display - Periodic maintenance screen - Display of spindle speed and T - Help function - Multi-language display - Operation history display - Parameter setting and display - Program comment display - Run hours / part count display - Self-diagnosis function - Servo setting screen - Spindle setting screen

PROGRAM INPUT	
- Absolute / incremental programming	
- Addition of custom macro common variable	
	0~#199, #500~#999
- Automatic coordinate system setting	
- Canned cycle for drilling / Turning	
- Canned cycle - Circular interpolation by R programming	
- Control in/out	
- Coordinate system setting	G50
- Coordinate system shift	
- Custom macro	
- Decimal point programming / Pocket calcula	ntor type decimal
point programming	(X axis
Diameter/radius programming Direct drawing dimension programming	(\Lambda dxi5
- Direct input of coordinate system shift	
- G code system A	
- G code system B/C	
- Input unit 10 time multiply	
- Label skip	
- Macro executor	
- Manual absolute on and off	.0.11.1
- Maximum program dimension	±9 digi
Multiple repetitive canned cycle Multiple repetitive canned cycle II	G70 - G76
- Optional block skip	9 piece
- Parity check	
- Plane selection	G17, G18, G19
- Program file name	32 characters
- Program stop / end(M00, M01 / M02, M30)	
- Programmable data input	G10
- Sequence number	N8 digi 10 folds nested
- SUB program call - Tape code : ISO / EIA auto recognition	EIA auto recognition
- Tape code : 150 / ElA dato recognition	LIA duto recognition
- Tape format for FANUC Series15	
- Work coordinate system	G52 - G59
TOOL FUNCTION / TOOL COMPENSATION	
- Automatic tool offset	
Direct input of offset value measured Direct input of offset value measured B	
- T-code function	T2+2 digits
- Tool geometry / wear compensation	12.12 0.8.0
- Tool life management	
- Tool Load Monitoring system *	
- Tool nose radius compensation	
- Tool offset	G43, G44, G49
- Tool offset pairs	±6 digits : 32 pairs
- Tool offset value counter input - Y-axis offset	
- I-UNIS UIISEL	
EDITING OPERATION	
- Back ground editting	
- Extended part program editing	
- Memory card edit & operation	
- Number of registered programs	500 ea
- Part program editing	(40 (254 1/4-+)
- Part program storage size	640 (256 Kbyte) n
- Program protect	
SETTING AND DISPLAY	
- Actual cutting feedrate display	
- Alarm display	
- Alarm history display	
Current position display	
- Current position display	
- Periodic maintenance screen	
 Periodic maintenance screen Display of spindle speed and T code at all so 	reens
	reens

31 characters

- Robot interface with PROFIBUS-DP

[]: PUMA 2100/2600 SY/LSY only *: According to the business contract made Doosan,

some regions have "Tool Load Monitoring system" as option.

DATA INPUT / OUTPUT - External key input	
- External data input	
- External work number search	15 point
- Memory card input/output	
- Reader/puncher interface	CH1.interfac
- RS232C interface	
- Automatic data backup	
- Screen hard copy	
OTHERS	
- Cycle start and lamp	40.41.61.16
- Display unit - Feed hold and lamp	10.4" Color LC
- NC and servo ready	
- PMC system	31iA-PM
- Reset / rewind	71//////
INTERFACE FUNCTION - Ethernet function	Embedded etherne
- Ethernet function	Lilibedded etilellie
OPERATION GUIDANCE FUNCTION	
- EZ Guidei (Conversational Programming So	olution)
OPTIONAL SPECIFICATIONS	
AXIS CONTROL	·
- Stored stroke 2 and 3	
- Stroke limit check before move	
OPERATION	a wa wu i wa d
 DNC operation(Reader/puncher interface i Manual handle feed 	s required) 2 uni
- Manual handle interruption	Z UIII
- Reference position shift	
- Tool retract and recover	
- 3rd / 4th reference point reurn - Circular threading	
- Multi eton ekin	
- Multi step skip	
- Multi step skip - Polygon machining with two spindle - Variable lead threading	
Multi step skip Polygon machining with two spindle Variable lead threading	
- Multi step skip - Polygon machining with two spindle - Variable lead threading FEED FUNCTION	
- Multi step skip - Polygon machining with two spindle - Variable lead threading FEED FUNCTION - External deceleration	
- Multi step skip - Polygon machining with two spindle - Variable lead threading FEED FUNCTION - External deceleration - Feed stop	
- Multi step skip - Polygon machining with two spindle - Variable lead threading FEED FUNCTION - External deceleration	G5.1 C
- Multi step skip - Polygon machining with two spindle - Variable lead threading FEED FUNCTION - External deceleration - Feed stop - Al Contour control I (Look-ahead block no. is Max.30)	
- Multi step skip - Polygon machining with two spindle - Variable lead threading FEED FUNCTION - External deceleration - Feed stop - Al Contour control I (Look-ahead block no. is Max.30) AUXILIARY / SPINDLE SPEED FUNCTIO	
- Multi step skip - Polygon machining with two spindle - Variable lead threading FEED FUNCTION - External deceleration - Feed stop - Al Contour control I (Look-ahead block no. is Max.30) AUXILIARY / SPINDLE SPEED FUNCTION	ON
- Multi step skip - Polygon machining with two spindle - Variable lead threading FEED FUNCTION - External deceleration - Feed stop - Al Contour control I (Look-ahead block no. is Max.30) AUXILIARY / SPINDLE SPEED FUNCTION PROGRAM INPUT - Addition of workpiece coordinate system p	ON
- Multi step skip - Polygon machining with two spindle - Variable lead threading FEED FUNCTION - External deceleration - Feed stop - Al Contour control I (Look-ahead block no. is Max.30) AUXILIARY / SPINDLE SPEED FUNCTION PROGRAM INPUT - Addition of workpiece coordinate system possible and the specific systems of the	ON
- Multi step skip - Polygon machining with two spindle - Variable lead threading FEED FUNCTION - External deceleration - Feed stop - Al Contour control I (Look-ahead block no. is Max.30) AUXILIARY / SPINDLE SPEED FUNCTION PROGRAM INPUT - Addition of workpiece coordinate system polygonia system control interruption type custom macro	DN pair 48 pair
- Multi step skip - Polygon machining with two spindle - Variable lead threading FEED FUNCTION - External deceleration - Feed stop - Al Contour control I (Look-ahead block no. is Max.30) AUXILIARY / SPINDLE SPEED FUNCTION PROGRAM INPUT - Addition of workpiece coordinate system polygon and control interruption type custom macro - Optional block skip (Soft operator's panel)	DN pair 48 pair
- Multi step skip - Polygon machining with two spindle - Variable lead threading FEED FUNCTION - External deceleration - Feed stop - Al Contour control I (Look-ahead block no. is Max.30) AUXILIARY / SPINDLE SPEED FUNCTION PROGRAM INPUT - Addition of workpiece coordinate system polygonia system control interruption type custom macro	DN pair 48 pai
- Multi step skip - Polygon machining with two spindle - Variable lead threading FEED FUNCTION - External deceleration - Feed stop - Al Contour control I (Look-ahead block no. is Max.30) AUXILIARY / SPINDLE SPEED FUNCTION PROGRAM INPUT - Addition of workpiece coordinate system produced to the control of the control o	DN pair 48 pai
- Multi step skip - Polygon machining with two spindle - Variable lead threading FEED FUNCTION - External deceleration - Feed stop - Al Contour control I (Look-ahead block no. is Max.30) AUXILIARY / SPINDLE SPEED FUNCTIO PROGRAM INPUT - Addition of workpiece coordinate system processed in the properties of the processed in t	DN pair 48 pair 9 piece
- Multi step skip - Polygon machining with two spindle - Variable lead threading FEED FUNCTION - External deceleration - Feed stop - Al Contour control I (Look-ahead block no. is Max.30) AUXILIARY / SPINDLE SPEED FUNCTION PROGRAM INPUT - Addition of workpiece coordinate system provided interruption type custom macro - Optional block skip (Soft operator's panel) - Pattern data input - Work coordinate system preset TOOL FUNCTION / TOOL COMPENSATION - Addition of tool pairs for tool life managem	pair 48 pai 9 piece
- Multi step skip - Polygon machining with two spindle - Variable lead threading FEED FUNCTION - External deceleration - Feed stop - Al Contour control I (Look-ahead block no. is Max.30) AUXILIARY / SPINDLE SPEED FUNCTION PROGRAM INPUT - Addition of workpiece coordinate system provided interruption type custom macro - Optional block skip (Soft operator's panel) - Pattern data input - Work coordinate system preset TOOL FUNCTION / TOOL COMPENSATION - Addition of tool pairs for tool life managem	pair 48 pair 9 piece
- Multi step skip - Polygon machining with two spindle - Variable lead threading FEED FUNCTION - External deceleration - Feed stop - Al Contour control I (Look-ahead block no. is Max.30) AUXILIARY / SPINDLE SPEED FUNCTION PROGRAM INPUT - Addition of workpiece coordinate system provided interruption type custom macro - Optional block skip (Soft operator's panel) - Pattern data input - Work coordinate system preset TOOL FUNCTION / TOOL COMPENSATION - Addition of tool pairs for tool life managem	pair 48 pair 9 piece
- Multi step skip - Polygon machining with two spindle - Variable lead threading FEED FUNCTION - External deceleration - Feed stop - Al Contour control I (Look-ahead block no. is Max.30) AUXILIARY / SPINDLE SPEED FUNCTION PROGRAM INPUT - Addition of workpiece coordinate system provided interruption type custom macro - Optional block skip (Soft operator's panel) - Pattern data input - Work coordinate system preset TOOL FUNCTION / TOOL COMPENSATION - Addition of tool pairs for tool life managem - Tool offset pairs 64 EDITING OPERATION - Number of registered programs	DN pair 48 pai 9 piece nent 128 pai 4/ 99 / 400 / 999 pai 1000 (512KB) 6
- Multi step skip - Polygon machining with two spindle - Variable lead threading FEED FUNCTION - External deceleration - Feed stop - Al Contour control I (Look-ahead block no. is Max.30) AUXILIARY / SPINDLE SPEED FUNCTION PROGRAM INPUT - Addition of workpiece coordinate system produced in the common state of the coordinate system produced in the coordinate system preset TOOL FUNCTION / TOOL COMPENSATION - Addition of tool pairs for tool life managem tool offset pairs - Tool offset pairs - Tool offset pairs - Number of registered programs - Part program storage length	DN pair 48 pai 9 piece nent 128 pai 4/ 99 / 400 / 999 pai 1000 (512KB) 6
- Multi step skip - Polygon machining with two spindle - Variable lead threading FEED FUNCTION - External deceleration - Feed stop - Al Contour control I (Look-ahead block no. is Max.30) AUXILIARY / SPINDLE SPEED FUNCTION - Addition of workpiece coordinate system properties of the system of th	DN pair 48 pai 9 piece nent 128 pai 4/ 99 / 400 / 999 pai 1000 (512KB) 6
- Multi step skip - Polygon machining with two spindle - Variable lead threading FEED FUNCTION - External deceleration - Feed stop - Al Contour control I (Look-ahead block no. is Max.30) AUXILIARY / SPINDLE SPEED FUNCTION PROGRAM INPUT - Addition of workpiece coordinate system provided in terruption type custom macro - Optional block skip (Soft operator's panel) - Pattern data input - Work coordinate system preset TOOL FUNCTION / TOOL COMPENSATION - Addition of tool pairs for tool life managem - Tool offset pairs - Tool offset pairs - Tool offset pairs - Part program storage length - Play back	DN pair 48 pai 9 piece nent 128 pai 4/ 99 / 400 / 999 pai 1000 (512KB) 6
- Multi step skip - Polygon machining with two spindle - Variable lead threading FEED FUNCTION - External deceleration - Feed stop - Al Contour control I (Look-ahead block no. is Max.30) AUXILIARY / SPINDLE SPEED FUNCTION PROGRAM INPUT - Addition of workpiece coordinate system programs - Automatic corner override - Interruption type custom macro - Optional block skip (Soft operator's panel) - Pattern data input - Work coordinate system preset TOOL FUNCTION / TOOL COMPENSATION - Addition of tool pairs for tool life managem - Tool offset pairs - Tool offset pairs - Automatic of registered programs - Part program storage length - Play back SETTING AND DISPLAY	DN pair 48 pai 9 piece nent 128 pai 4/ 99 / 400 / 999 pai 1000 (512KB) 6
- Multi step skip - Polygon machining with two spindle - Variable lead threading FEED FUNCTION - External deceleration - Feed stop - Al Contour control I (Look-ahead block no. is Max.30) AUXILIARY / SPINDLE SPEED FUNCTION PROGRAM INPUT - Addition of workpiece coordinate system provided in terruption type custom macro - Optional block skip (Soft operator's panel) - Pattern data input - Work coordinate system preset TOOL FUNCTION / TOOL COMPENSATION - Addition of tool pairs for tool life managem - Tool offset pairs - Tool offset pairs - Tool offset pairs - Part program storage length - Play back	DN pair 48 pair 9 piece nent 128 pair 4/ 99 / 400 / 999 pair 1000 (512KB) è
- Multi step skip - Polygon machining with two spindle - Variable lead threading FEED FUNCTION - External deceleration - Feed stop - Al Contour control I (Look-ahead block no. is Max.30) AUXILIARY / SPINDLE SPEED FUNCTION PROGRAM INPUT - Addition of workpiece coordinate system programment of the programment of th	9 piece 1 9 piece 1 128 pair 4 / 99 / 400 / 999 pair 1000 (512KB) e 1280 / 2560 / 5120 r
- Multi step skip - Polygon machining with two spindle - Variable lead threading FEED FUNCTION - External deceleration - Feed stop - Al Contour control I (Look-ahead block no. is Max.30) AUXILIARY / SPINDLE SPEED FUNCTION PROGRAM INPUT - Addition of workpiece coordinate system properties of the system of t	DN pair 48 pair 9 piece nent 128 pair 4/ 99 / 400 / 999 pair 1000 (512KB) è 1280 / 2560 / 5120 i Only for 1 pat
- Multi step skip - Polygon machining with two spindle - Variable lead threading FEED FUNCTION - External deceleration - Feed stop - Al Contour control I (Look-ahead block no. is Max.30) AUXILIARY / SPINDLE SPEED FUNCTION PROGRAM INPUT - Addition of workpiece coordinate system programment of the programment of th	DN pair 48 pair 9 piece nent 128 pair 4/ 99 / 400 / 999 pair 1000 (512KB) è
- Multi step skip - Polygon machining with two spindle - Variable lead threading FEED FUNCTION - External deceleration - Feed stop - Al Contour control I (Look-ahead block no. is Max.30) AUXILIARY / SPINDLE SPEED FUNCTIO PROGRAM INPUT - Addition of workpiece coordinate system processes and stop of the processes and stop of th	DN pair 48 pair 9 piece nent 128 pair 4/ 99 / 400 / 999 pair 1000 (512KB) è 1280 / 2560 / 5120 i Only for 1 pat
- Multi step skip - Polygon machining with two spindle - Variable lead threading FEED FUNCTION - External deceleration - Feed stop - Al Contour control I (Look-ahead block no. is Max.30) AUXILIARY / SPINDLE SPEED FUNCTION - Addition of workpiece coordinate system p - Automatic corner override - Interruption type custom macro - Optional block skip (Soft operator's panel) - Pattern data input - Work coordinate system preset TOOL FUNCTION / TOOL COMPENSATION - Addition of tool pairs for tool life managem - Tool offset pairs - Tool offset pairs - Part program storage length - Play back SETTING AND DISPLAY - Directory display of floppy cassette DATA INPUT/OUTPUT - Fast ethernet / Data server	DN pair 48 pair 9 piece nent 128 pair 4/ 99 / 400 / 999 pair 1000 (512KB) è 1280 / 2560 / 5120 i Only for 1 pat

NC Unit Specifications

DOOSAN-Fanuc i series

DOOS/ III Tana	crocnes
AXES CONTROL	
- Controlled path	1 path [2 path]
- Controlled axes	X, Z, C, Y [C2, B]
- Simultaneous controlled axes	4 axes
- Axis control by PMC	4 40.03
- Backlash compensation	0 ~ ±9999 pulses
- Backlash compensation for each	0 ±//// puiscs
rapid traverse and cutting feed	
- Chamfering on / off	
- Cs contouring control	
- HRV2 control	
- Least input command	0.001 / 0.0001 mm/inch
- Machine lock	All axis / each axis
- Mirror image	·
- Overtravel	
- Stored pitch error compensation	
- Stored stroke check 1	
- Chuck and tail stock barrier	
- Stored stroke 2 and 3	
- Stroke limit check before move	
- Torque control	
OPERATION	
- Automatic operation (memory)	
- MDI operation	
- DNC Operation with Memory card	
- Dry run	
- Handle incremental feed	X1, X10, X100
- Program restart	
- Wrong operation prevention	
- JOG feed	
- Manual handle feed	1unit
- Manual intervention and return	
- Manual reference position return	
- Program number search	
- Refernce position setting without	dog
- Sequence number search	

INTERPOLATION FUNCTIONS

- Reference position shift

- Manual handle interruption

- Single block

INTERPOLATION FUNCTIONS	
- Nano interpolation	
- Positioning	G00
- 1st. Reference position return	Manual, G28
- 2nd. reference position return	G30
- Circular interpolation	G02
- Continuous threading	
- Cylindrical interpolation	
- Dwell (per sec)	G04
- Helical interpolation	
- Linear interpolation	G01
- Multiple threading	
- Polar coordinate interpolation	
- Reference position return check	G27
- Skip	G31
- Thread cutting / Synchronous cutting	
- Thread cutting retract	
- Torque limit skip	
- 3rd / 4th reference point reurn	
- Polygon machining with two spindle	
- Variable lead threading	

- DNC operation (Reader / puncher interface is required)

FEED FUNCTION

TELDTUNCTION	
- Automatic acceleration / deceleration	
- Cutting feedrate clamp	
- Feedrate override (10% unit)	0 - 200 %
- Jog feed override (10% unit)	0 - 2000 mm/min
- Override cancel	
- Rapid traverse override	F0, 25, 100 %

AUXILIARY / SPINDLE SPEED FUNCTION	
- Spindle orientation	
- Actual spindle speed output	
- Auxiliary function lock	
- Constant surface speed control	
- M-code function	M3 digits
- Multi spindle control	
- Rigid tapping	
- S-code function	S4 / S5 digits
- Spindle serial output	S4 / S5 digits
- Spindle speed override	0 - 150 %
- [Spindle sychronous control]	

PROGRAM INPUT

41 1 1 1 1 1		
- Absolute / incremental programming		
- Addition of custom macro common variables		
	#100~#199,#500~#999	
- Automatic coordinate system setting		
- 1 1 2 1 111 1- 1		

- Automatic coordinate system setting - Canned cycle for drilling / Turning - Circular interpolation by R programming - Coordinate system setting - Custom macro - Pocket calculator type decimal point programming - Diameter/radius programming (X axis)
- Circular interpolation by R programming - Coordinate system setting - Custom macro - Pocket calculator type decimal point programming
Coordinate system setting Custom macro Pocket calculator type decimal point programming
- Custom macro - Pocket calculator type decimal point programming
- Pocket calculator type decimal point programming
,, , , , , ,
- Diameter/radius programming (X axis)
Diameter, radias programming (radis)
- Direct drawing dimension programming

- Direct input of coordinate system sinit
- G code system A / B / C
- Label skip
- Macro executor

- Manual absolute on and off	
- Maximum program dimension	±9 digit
- Multiple repetitive canned cycle	G70 - G76
- Multiple repetitive canned cycle II	

- Optional block skip	9 piec
- Parity check	
- Plane selection	G17, G18, G19
- Program file name	32 character
- Program stop / end (M00, M01 / M02, M30)	
- Programmable data input	G10

- Programmable data input	G10
- Sequence number	N8 digit
- SUB program call	10 folds nested
- Work coordinate system	G52-G59
- Interruption type custom macro	
- Optional block skip	9 piece

TOOL FUNCTION / TOOL COMPENSATION

- Pattern data input

- Automatic tool offset	
- T-code function	T2+2 digits
- Tool geometry / wear compensation	
- Tool life management	
- Tool Load Monitoring system *	
- Tool nose radius compensation	
- Tool offset	G43, G44, G49
- Tool offset pairs	+6 digits · 6/1 nairs

Tool offset value counter input	
Y-axis offset	

EDITING OPERATION

- Number of registered programs	400 ea
- Part program editing	
- Part program storage size	1280m (512kB)
- Play hack	

SETTING AND DISPLAY

- Alarm history display	
- Multi-language display	
- Program comment display	31 character
- Run hours / part count display	
- Self-diagnosis function	
- Operating monitor screen	

DATA INPUT / OUTPUT

- Laternal work number Search	13 points
- Memory card input/output	
- RS232C interface	
- Automatic data backup	
- Screen hard copy	

OTHERS	
- Cycle start and lamp	
- Display unit	10.4" Color LCD
- Feed hold and lamp	
- MDI unit	
- NC and servo ready	
- PMC system	

INTERFACE FUNCTION

OPERATION GUIDANCE FUNCTION

- EZ Guidei (Conversational Programming Solution)

OPTIONAL SPECIFICATIONS

INTERPOLATION FUNCTIONS

- Multi step skip

FEED FUNCTION

- Advanced preview control

TOOL FUNCTION / TOOL COMPENSATION

- Tool offset pairs	99 / 200 pairs

DATA INPUT / OUTPUT

- Fast ethernet / Data server Only for 1 path

ROBOT INTERFACE

- Robot interface with PMC I/O module (Hardware between PMC I/O mudules)
- Robot interface with PROFIBUS-DP

[]: PUMA 2100/2600 SY/LSY only

*: According to the business contract made Doosan, some regions have "Tool Load Monitoring system" as option.





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